



## Summer Fellowship Report

On

Python code for different sections of IS 800:2007  
and  
Preparing DDCL for Truss connection

Submitted by

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# Chapter 1

## Introduction

### 1.1 FOSSEE Summer Research Fellowship

FOSSEE project promotes the use of FOSS (Free/Libre and Open Source Software) tools to improve quality of education in our country. FOSSEE encourages the use of FOSS tools through various activities to ensure availability of competent free software equivalent to commercial (paid) softwares.

The [FOSSEE](#) project is a part of the National Mission on Education through Infrastructure and Communication Technology(ICT), Ministry of Human Resources and Development, Government of India.

Osdag is one such open source software which comes under the FOSSEE project. Osdag internship is provided through FOSSEE project. Any UG/PG/PhD holder can apply for this internship. And the selection will be based on a screening task.

### 1.2 What is Osdag?

Osdag is Free/Libre and Open Source Software being developed for design of steel structures. Its source code is written in Python, 3D CAD images are developed using PythonOCC. Github is used to ensure smooth workflow between different modules and team members. It is in a path where people from around the world would be able to contribute to its development. FOSSEE's "Share alike" policy would improve the standard of the software when the source code is further modified based on the industrial and educational needs across the country.

Design and Detailing Checklist (DDCL) for different connections, mem-

bers and structure designs is one of the important bi-products of this project. It would create a repository and design guide book for steel construction based on Indian Standard codes and best industry practices.

### **1.3 Who can use ?**

Osdag is created both for educational purpose and industry professionals. As Osdag is currently funded by MHRD, Osdag team is developing software in such a way that it can be used by the students during their academics and to give them a better insight look in the subject.

Osdag can be used by anyone starting from novice to professionals. It's simple user interface makes it flexible and attractive than other software. Video tutorials are available to help get started. The video tutorials of Osdag can be accessed [here](#).

## Chapter 2

# Python Code of IS 800: 2007

We are creating library for fuctions of IS 800: 2007, so that it can be used directly for compiling code of various modules of Osdag in future. So, I converted sections of IS 800: 2007 to python codes.

For creating python codes google strings are used to explain variables and output,where 'Args' section is used for defining variables and 'Return' is for output for each functions of IS 800:2007, as shown in figure;

```
# cl.7.1.2.1 design compressive stress of axially loaded member
@staticmethod
def cl_7_1_2_1_design_compressive_stress(K_L,alpha,E,f_y,r,gamma_m0):
    """
        Calculation of design compressive stress
    Args:
        K_L - Effective length of compression member in mm
        alpha - Imperfection factor
        E - Young's Modulus of Elasticity in N/mm**2
        f_y - Yield Stress in N/mm**2
        r - radius of gyration in mm

    Return:
        f_cd - Design strength of compression member in N/mm**2

    Note:
        Reference:
        IS 800:2007, cl.7.1.2.1
    """

    f_cc = (math.pi ** 2 * E) / (K_L / r) ** 2 #euler buckling stress
    lambda_ = math.sqrt(f_y / f_cc) #non-dimensional slenderness ratio
    phi = 0.5 * (1 + alpha * (lambda_ - 0.2) + lambda_ ** 2)
    srf = 1 / (phi + math.sqrt(phi ** 2 - lambda_ ** 2)) #stress reduction factor,kai
    f_cd = min( f_y / gamma_m0 * srf, f_y / gamma_m0)
    return f_cd
```

Tables of each sections of IS 800:2007 are stored as dictionary in python code, as shown below;

```

# Table 5 Partial Safety Factors for Materials, gamma_m (dict)
class IS800_2007(object):
    cl_5_4_1_Table_5 = {"gamma_m0": {'yielding': 1.10, 'buckling': 1.10},
                         "gamma_m1": {'ultimate_stress': 1.25},
                         "gamma_mf": {'shop': 1.25, 'field': 1.25},
                         "gamma_mb": {'shop': 1.25, 'field': 1.25},
                         "gamma_mr": {'shop': 1.25, 'field': 1.25},
                         "gamma_mw": {'shop': 1.25, 'field': 1.50}
    }

```

## 2.1 Python Code for Section 6 IS 800: 2007

Tension members are linear members in which axial forces acts and cause elongation, how such members should be designed is given in Section 6 ('Design of Tension Members') of IS 800: 2007 and its functions are converted into python codes so that it can be directly used in future for the development of module for design of tension Member in Osdag. It's Python codes is attached vide [Appendix - A](#).

## 2.2 Python Code for Section 7 IS 800: 2007

Compression members are the members which can take axial compressive load. These members usually fail by flexure buckling and section 7 of IS 800: 2007 explains how such members should be designed to resist buckling failure. Python code for this is attached vide [Appendix - B](#)

## 2.3 Python Code for Section 8 IS 800: 2007

Members subjected to predominant bending must have adequate design strength to resist bending moment and shear force and how such member should be designed properly so that it can work efficiently in its design period is explained in section 8 ("Design of Members subjected to bending") of IS 800: 2007. Python code for this is attached vide [Appendix - C](#)

## **2.4 Python Code for Annex E IS 800: 2007**

Factors affecting elastic critical moment and it's calculation constitutes Annex E ("Elastic Lateral Torsional Buckling") of IS 800: 2007.

Python code for this is attached in vide [Appendix - D](#)

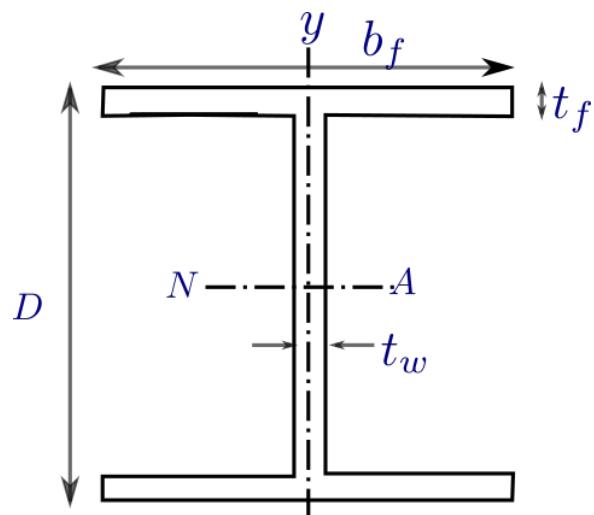
Git link for this is attached here: <https://github.com/Rachnagupta29/0sdag/pull/1>

## Chapter 3

# Sectional Properties of I- section

### 3.1 Creating class for sectional properties of I section

Class of sectional properties for I section is created so that Osdag software can also be used for the design of sections which are not in Steel Tables. And users will have freedom to design section according to their preference.



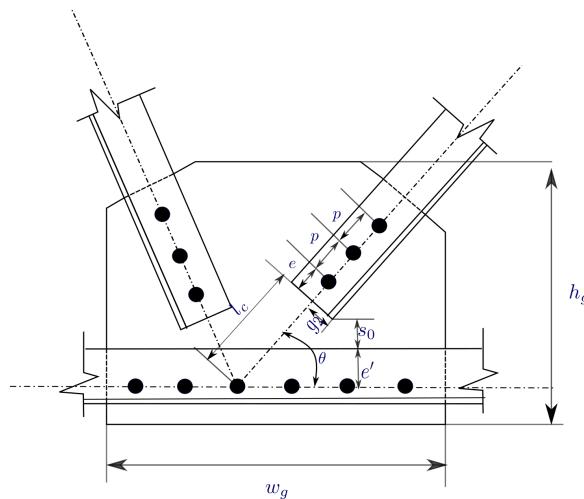
Python code for this is attached vide [Appendix - E](#)

# Chapter 4

## Preparation of DDCL

### 4.1 DDCL for Bolted Truss connection

I have made DDCL for Bolted Truss connection, which is going to be the design module of Osdag software in future. By this designers will be able to design efficient Bolted connection for truss for various geometrical arrangements.



The DDCL of Truss connection is attached vide [Appendix - F](#)

### 4.2 DDCL for Welded Truss connection

I prepared DDCL for weld connection, in which gusset plate is connected to members through welding in truss connection.

The DDCL of Truss connection is attached vide [Appendix -G](#)

# **Chapter 5**

# **Reference**

- IS 800:2007 Indian Standard Code of Practice for General Construction in Steel, 2007.
- IS 808:1989 Indian Standard Code of Practice for Dimensions of Hot Rolled Steel Beam, Column, Channel and Angle Sections, 1989.
- US Department of Transportation Federal Highway Administration, Guidelines for Design and Rating of Gusset-Plate Connections for Steel Truss Bridges.
- William A. et al, The Whitmore Section.
- Institute of Steel Development and Growth. Hand Book on Structural Steel Detailing, 2018a.
- N.Subramanian Design of Steel Structures. Oxford University Press, 13 edition, 2013.
- American Institute of Steel Construction. Steel Construction Manual, 13 edition, 2017.

# Chapter 6

## Conclusion

The internship enriched me with knowledge, skills and gave me a chance to interact with new people, which helped me to achieve several learning goals, and have moved a step further in achieving other. I got insight into how design is done in field and the adverse factors that need to be considered. Internship has proved to be satisfactory and it has allowed as an opportunity to get an exposure of the practical implementation of theoretical fundamentals.

I learned technical things, like Osdag, Basics of Python, Latex, Git and Git hub

Throughout the internship, I found that several things are important:

- **Critical and Analytical Thinking**

To organize our tasks and assignment, we need to analyse our problems and assignment, and to formulate a good solution to the problem. We would have to set contingency plan for the solution, so that we are well prepared for the unforeseeable situations.

- **Time Management**

As overall project staff and programmer are always racing against tight time line and packed schedule, a proper time management will minimize facing overdue deadlines. An effective time management allows us to do our assignment efficiently and meet our schedules. Scheduling avoids time wastage and allows us to plan ahead, and gaining more as a result.

- **Goal Management**

It is better to sub-divide the goals to a few achievable tasks, so that we will be gaining more confidence by accomplishing those tasks.

- **Colleague Interactions**

In working environment, teamwork plays a vital role in contributing to a strong organization. Teamwork is also essential in reaching the goals of the organization as an entity. Thus, communicating and sharing is much needed in the working environment. Therefore, we should be respecting each other in work, and working together as a team, instead of working alone. This is because working together as a team is easier in reaching our targets, rather than operating individually.

I would like to once again appreciate everyone who has made my internship training a superb experience.

# Appendices

## Appendix A

# Python Code for Section 6 IS: 800 2007

```
1 import math
2 """      SECTION 6      DESIGN OF TENSION MEMBERS      """
3 # Table 5 Partial Safety Factors for Materials, gamma_m (dict)
4 class IS800_2007(object):
5     cl_5_4_1_Table_5 = {"gamma_m0": {'yielding': 1.10, 'buckling': 1.10},
6                         "gamma_m1": {'ultimate_stress': 1.25},
7                         "gamma_mf": {'shop': 1.25, 'field': 1.25},
8                         "gamma_mb": {'shop': 1.25, 'field': 1.25},
9                         "gamma_mr": {'shop': 1.25, 'field': 1.25},
10                        "gamma_mw": {'shop': 1.25, 'field': 1.50}}
11
12
13
14 # DESIGN OF TENSION MEMBER
15 # cl 6.1 Tension
16 @staticmethod
17 def cl_6_1_Design_strength_of_tension_member(T_dg, T_dn, T_db):
18     """
19         Calculation of Design Strength of the member as per cl.6.1
20     Args:
21         T_dg - design strength due to yielding of gross section in N (float),
22         T_dn - design rupture strength of critical section in N (float),
23         T_db - design strength due to block shear in N (float)
24
25     Return:
26         T_d - design strength of the number under axial tension in N (float),
27     Note:
28         References:
29             IS800:2007, cl.6.1
30     """
31     T_d = min(T_dg, T_dn, T_db)
32     return T_d
33
34
35 #cl.6.2 Design Strength due to yielding of Gross Section
36 @staticmethod
37 def cl_6_2_Design_strength_of_member_due_to_yielding_of_gross_section(A_g,
38                         f_y):
39     """
40         Calculate the design strength due to yielding of gross section as
```

```

    per cl.6.2
40
41     Args:
42         A_g- Gross area of cross section[in sq.mm](float)
43         f_y- Yield stress of the material in Mpa (float)
44
45     Return:
46         T_dg - Design strength of member due to yielding of gross section
47         in N(float)
48
49     Note:
50         Reference:
51             IS 800:2007, cl.6.2
52
53     """
54
55     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
56     T_dg = A_g * f_y / gamma_m0
57     return T_dg
58
59 # cl.6.3 Design Strength Due to Rupture of Critical Section
60 # cl.6.3.1 Plates
61 @staticmethod
62 def cl_6_3_1_design_strength_in_tension(b, n, d_h, p_s, g, f_u, t):
63     """
64         Calculate the design strength in tension of a plate as per cl.6.3.1
65     Args:
66         A_n- net effective area of the member[in sq.mm](float)
67         f_u- ultimate stress of the material in Mpa(float)
68         b,t- width and thickness of the plate,respectively[in mm](float)
69         d_h- diameter of the bolt hole[2mm in addition to the diameter of
70             the hole,
71                 in case the directly punched holes[in mm](float)
72         g- gauge length between the bolt holes[in mm](float list)
73         p_s- staggered pitch length between line of bolt holes[in mm](float
74             list)
75         n- number of bolt holes in the critical section (int)
76
77     Return:
78         T_dn - design strength in tension of a plate in N(float)
79
80     Note:
81         Reference:
82             IS 800:2007, cl.6.3.1
83
84     """
85
86     gamma_m1 = IS800_2007.cl_5_4_1_Table_5["gamma_m1"]['ultimate_stress']
87     sum_value = 0
88     for i in range(n - 1):
89         sum_value += (p_s[i] * p_s[i]) / (4 * g[i])
90
91     A_n = (b - n * d_h + sum_value) * t
92     T_dn = 0.9 * A_n * f_u / gamma_m1
93     return T_dn
94
95 # cl.6.3.2 Threaded Rods
96 @staticmethod
97 def cl_6_3_2_design_strength_of_threaded_rods_in_tension(A_n, f_u):
98     """
99         Calculate the design strength of threaded rods in tension as per cl

```

```

.6.3.2
97
98     Args:
99         A_n- net root area at the threaded section [in sq.mm](float)
100        f_u- ultimate stress of the material in Mpa(float)
101
102    Return:
103        T_dn - design strength of threaded rods in tension in N(float)
104
105    Note:
106        Reference:
107            IS800:2007, cl.6.3.2
108    """
109
110    gamma_m1 = IS800_2007.cl_5_4_1_Table_5["gamma_m1"]['ultimate_stress']
111    T_dn = 0.9 * A_n * f_u / gamma_m1
112    return T_dn
113
114
115 # cl.6.3.3 Single Angles
116 @staticmethod
117 def cl_6_3_3_design_strength_of_an_angle_connected_through_one_leg(A_nc,
118     f_u, w, t, f_y, b_s, L_c, A_go):
119     """
120         Calculation of design strength of an angle connected through one
121         leg as per cl.6.3.3
122
123     Args:
124         w - outstanding leg width in mm(float)
125         b_s - shear lag width in mm(float)
126         L_c - length of the end connection, that is the distance between
127             the outermost
128                 bolts in the end joint measured along the load direction or
129                 length of the weld
130                     along the load direction in mm(float)
131         A_nc - net area of the connected leg[in sq. mm](float)
132         A_go - gross area of the outstanding leg[in sq. mm](float)
133         t - thickness of the leg in mm(float)
134         f_u- ultimate strength of material in Mpa(float)
135
136     Return:
137         T_dn - design strength of an angle connected through onw leg in N(
138             float)
139
140     Note:
141         Reference:
142             IS800:2007, cl.6.3.3
143
144     """
145
146     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
147     gamma_m1 = IS800_2007.cl_5_4_1_Table_5["gamma_m1"]['ultimate_stress']
148
149     X = max(0.7, f_u * gamma_m0 / f_y * gamma_m1)
150     beta = min(X, 1.4 - 0.076 * (w / t) * (f_y / f_u) * (b_s / L_c))
151     T_dn = (0.9 * A_nc * f_u / gamma_m1) / (beta * A_go * f_y / gamma_m0)
152     return T_dn
153
154
155 # cl 6.3.3 For preliminary sizing
156 @staticmethod

```

```

152 def cl_6_3_3_1_design_strength_of_net_section(n, A_n, f_u):
153     """
154         Calculation of rupture strength of net section for preliminary sizing
155         as per cl.6.3.3
156
157     Args:
158         A_n - net area of the total cross-section[in sq.mm](float)
159         f_u - ultimate tensile strength pf material in Mpa(float)
160         n - number of bolts (int)
161
162     Return:
163         T_dn - design strength of net section for preliminary sizing in N(
164             float)
165
166     Note:
167         Reference:
168             IS800:2007 cl.6.3.3
169         """
170
171     if n in [1, 2]:
172         alpha = 0.6
173     else:
174         if n == 3:
175             alpha = 0.7
176         else:
177             alpha = 0.8
178
179
180     gamma_m1 = IS800_2007.cl_5_4_1_Table_5["gamma_m1"]['ultimate_stress']
181     T_dn = alpha * A_n * f_u / gamma_m1
182     return T_dn
183
184 #cl.6.3.4 Other Section
185 #cl.6.4.1 Block shear strength of bolted connections
186 @staticmethod
187 def cl_6_4_1_block_shear_strength(A_vg, A_vn, A_tg, A_tn, f_u, f_y):
188     """
189         Calculation of the block shear strength of bolted connection as per
190         cl.6.4.1
191
192     Args:
193         A_vg - Minimum gross in shear along bolt line parallel to external
194             force [in sq.mm](float)
195         A_vn - Minimum net area in shear along bolt line parallel to
196             external force[in sq.mm](float)
197         A_tg - Minimum gross area in tension from the bolt hole to the toe
198             of the angle,
199             end bolt line, perpendicular to the line of force,
200             respectively [ in sq.mm](float)
201         A_tn - Minimum net area in tension from the bolt hole to the toe of
202             the angle,
203             end bolt line, perpendicular to the line of force,
204             respectively [in sq.mm]
205         f_u - Ultimate stress of the plate ,material in Mpa(float)
206         f_y - Yield stress of the plate material in Mpa(float)
207
208     Return:
209         T_db - block shear strength of bolted connection in N (float)
210
211     Note:
212         Reference:
213             IS800:2007, cl.6.4.1

```

```

204 """
205 gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
206 gamma_m1 = IS800_2007.cl_5_4_1_Table_5["gamma_m1"]['ultimate_stress']
207 T_db1 = A_vg * f_y / (math.sqrt(3) * gamma_m0) + 0.9 * A_tn * f_u /
208 gamma_m1
209 T_db2 = 0.9 * A_vn * f_u / (math.sqrt(3) * gamma_m1) + A_tg * f_y /
210 gamma_m0
211 T_db = min(T_db1, T_db2)
212
213 return T_db
214 # =====

```

## Appendix B

# Python Code for Section 7 IS: 800 2007

```
1     """ SECTION 7      DESIGN OF COMPRESSION MEMBERS """
2     import math
3     # Table 5 Partial Safety Factors for Materials, gamma_m (dict)
4     class IS800_2007(object):
5         cl_5_4_1_Table_5 = {"gamma_m0": {'yielding': 1.10, 'buckling': 1.10},
6                             "gamma_m1": {'ultimate_stress': 1.25},
7                             "gamma_mf": {'shop': 1.25, 'field': 1.25},
8                             "gamma_mb": {'shop': 1.25, 'field': 1.25},
9                             "gamma_mr": {'shop': 1.25, 'field': 1.25},
10                            "gamma_mw": {'shop': 1.25, 'field': 1.50}}
11
12
13
14     # cl 7.1 Design Strength
15     # cl.7.1.2
16     @staticmethod
17     def cl_7_1_2_design_compressive_strength_of_a_member(A_c, f_cd):
18         """
19             Calculation of design compressive strength
20             Args:
21                 A_c - Effective sectional area (in square mm)
22                 f_cd - Design Compressive stress(in N)
23
24             Return:
25                 P_d - Design Compressive Strength of a member (in N)
26
27             Note:
28                 References:
29                 IS800:2007 cl.7.2
30         """
31
32         P_d = f_cd * A_c
33         return P_d
34
35
36     # cl 7.1.2.1 design compressive stress of axially loaded member
37     @staticmethod
38     def cl_7_1_2_1_design_compressive_stress(K_L, alpha, E, f_y, r, gamma_m0):
39         """
40             Calculation of design compressive stress
41             Args:
42                 K_L - Effective length of compression member in mm
```

```

43         alpha - Imperfection factor
44         E - Young's Modulus of Elasticity in N/mm**2
45         f_y - Yield Stress in N/mm**2
46         r - radius of gyration in mm
47
48     Return:
49         f_cd - Design strength of compression member in N/mm**2
50
51     Note:
52         Reference:
53             IS 800:2007, cl.7.1.2.1
54
55
56     f_cc = (math.pi ** 2 * E) / (K_L / r) ** 2 #euler buckling stress
57     lambda_ = math.sqrt(f_y / f_cc) #non-dimensional slenderness ratio
58     phi = 0.5 * (1 + alpha * (lambda_ - 0.2) + lambda_ **2)
59     srf = 1 / (phi + math.sqrt(phi ** 2 - lambda_ ** 2)) #stress
reduction factor ,kai
60     f_cd = min( f_y / gamma_m0 * srf, f_y / gamma_m0)
61     return f_cd
62
63
64 # cl 7.1.2.2 Calculation of buckling class of given cross-section
65 @staticmethod
66 def cl_7_1_2_2_Table_10_Buckling_class_of_cross_section(Cross_section,
t_f,t_w,h,b_f):
67
68     Defining Buckling Class of Cross-Section
69     Args:
70         Cross_section - Either 'Rolled_I_Section' or 'Welded_I_Section',
71                         or 'Hot_rolled_hollow' or 'cold_Formed_hollow',
72         or 'Welded_Box_Section',
73                         or 'Channel,Angle,T,Solid Section' or '
74         Built_up_Member'
75
76         h- Depth of the section in mm
77         b_f - width of flange or width of section in case of welded box
section(mm)
78         t_f - Thickness of flange in mm
79         t_w - Thickness of web in mm
80
81     Return:
82         Dictionary of Buckling axis and Buckling class with Buckling
axis as key
83
84     Note:
85         Reference:
86             IS 800:2007, cl.7.1.2.2, Table_10
87
88     if Cross_section == "Rolled_I_Section":
89         if h / b_f > 1.2 :
90             if t_f <= 40:
91                 return {'z-z': 'a','y-y': 'b'}
92
93             if t_f>40 and t_f<=100:
94                 return {'z-z': 'b','y-y': 'c'}
95
96         if h / b_f <= 1.2:
97             if t_f <= 100:
98                 return {'z-z': 'b','y-y': 'c'}

```

```

98         if t_f>100:
99             return {'z-z': 'd','y-y': 'd'}
100
101     if Cross_section == "Welded_I_Section":
102         if t_f <= 40:
103             return {'z-z': 'b','y-y': 'c'}
104         if t_f>40:
105             return {'z-z': 'c','y-y': 'd'}
106
107     if Cross_section == "Hot_rolled_hollow":
108         return {'z-z': 'a','y-y': 'a'}
109
110     if Cross_section == "cold_Formed_hollow":
111         return {'z-z': 'b','y-y': 'b'}
112
113     if Cross_section == "Welded_Box_Section":
114         Buckling_Class_1 = 'b'
115         Buckling_Class_2 = 'b'
116
117         if b_f / t_f < 30:
118             Buckling_Class_1 = "c"
119
120         if h / t_w < 30:
121             Buckling_Class_2 = "c"
122
123         return {'z-z': Buckling_Class_1,'y-y': Buckling_Class_2}
124
125     if Cross_section == "Channel_Angle_T_Solid_Section" or
126     Cross_section == "Built_up_Member":
127         return {'z-z': 'c','y-y': 'c'}
128
129 #Imperfection Factor , alpha
130 # alpha for a given buckling class , 'a' , 'b' , 'c' or 'd'
131 cl_7_1_Table_7_alpha = {
132     'a': 0.21,
133     'b': 0.34,
134     'c': 0.49,
135     'd': 0.76,
136 }
137
138 #Table 11 Effective Length of Prismatic Compression Members
139 @staticmethod
140 def cl_7_2_2_table11_effective_length_of_prismatic_compression_members(
L,BC=[]):
141
142     """
143         Effective length of Prismatic Compression Member when the
144         boundary conditions in the plane of buckling
145         can be assessed
146
147     Args:
148         BC - linked list of Boundary Conditions
149             =[BC_translation_end1,BC_rotation_end1,BC_translation_end2
150             ,BC_rotation_end2]
151         L - Length of the Compression member in mm
152
153     Return:
154         K_L - Effective length of Compression Member in mm
155
156     Note:

```

```

155     Reference:
156     IS 800:2007, cl.7.2.2, Table_11
157     """
158
159     if BC == ['Restrained', 'Restrained', 'Free', 'Free'] or BC == ['
160     Restrained', 'Free', 'Free', 'Restrained']:K_L = 2.0 * L
161     elif BC == ['Restrained', 'Free', 'Restrained', 'Free']:K_L = L
162     elif BC == ['Restrained', 'Restrained', 'Free', 'Restrained']:K_L =
163     1.2 * L
164     elif BC == ['Restrained', 'Restrained', 'Restrained', 'Free']:K_L =
165     0.8 * L
166     elif BC == ['Restrained', 'Restrained', 'Restrained', 'Restrained']:
167     K_L = 0.65 * L
168     return K_L
169
170
171
172 # cl 7.1.2.1 design compressive stress of axially loaded member
173 @staticmethod
174 def design_compressive_stress(f_y, r):
175
176     """
177     Calculation of design compressive stress
178     Args:
179         K_L - Effective length of compression member in mm
180         alpha - Imperfection factor
181         E - Young's Modulus of Elasticity in N/mm**2
182         f_y - Yield Stress in N/mm**2
183         r - radius of gyration of the section in mm
184
185     Return:
186         f_cd - Design strength of compression member in N/mm**2
187
188     Note:
189         Reference:
190         IS 800:2007, cl.7.1.2.1
191         """
192
193     Buckling_Class =
194     cl_7_1_2_2_Table_10_Buckling_class_of_cross_section(Cross_section, h,
195     b_f, t_f)
196     alpha = cl_7_1_Table_7_alpha["Buckling_Class"]["alpha"]
197     K_L = cl_7_2_2_effective_length_of_prismatic_Compression_members(
198     At_one_end_Translation, At_one_end_Rotation,
199
200     At_other_end_Translation,
201
202     At_other_end_Rotation, L)
203     f_cc = (pi * pi * E) / (K_L / r) ** 2
204     lambda_c = math.sqrt(f_y / f_cc)
205     phi = 0.5 * (1 + (alpha * (lambda_c - 0.2)) + (lambda_c * lambda_c))
206     srf = 1 / (phi + math.sqrt(phi ** 2 - lambda_c ** 2))
207     f_cd = min(((f_y / gamma_m0) * srf), f_y / gamma_m0)
208     return f_cd
209
210
211 # Design of Column Base
212 #cl.7.4.3 thickness of column base
213 @staticmethod
214 def cl_7_4_3_1_Calculation_of_thickness_of_column_base(w,a,b,t_f,f_y):
215
216     """
217     Calculation of thickenss of Column base

```

```

207     Args:
208         w - uniform pressure from below on the slab base in mm
209         a - Larger Projection in mm
210         b - Smaller Projection in mm
211         f_y - Yield Stress in N/mm**2
212         t_f - Thickness of flange of Compression member in mm
213
214     Return:
215         t_s - thickness of rectangular slab column base in mm
216
217     Note:
218         Reference:
219             IS 800:2007 cl.7.4.3.1,
220
221         """
222
223     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yield_stress']
224     t_s = max(t_f, math.sqrt(2.5 * w * (a ** 2 - 0.3 * b ** 2) *
225     gamma_m0 / f_y))
226     return t_s
227
228 #cl.7.5.1.2 Loaded through one angle
229 #Table 12 - evaluation of constants K1,K2,K3 for effective slenderness
230 #ratio
231 @staticmethod
232 def cl_7_5_1_2_table12_constant_K_1_K_2_K_3(
233     No_of_Bolts_at_Each_End_Connection, Connecting_member_Fixity):
234
235     """Value of constant K_1,K_2, K_3
236     Args:
237         No_of_Bolts_at_Each_End_Connection - Either more than 2 or 1,
238         Fixity - Either Fixed or Hinged.
239
240     Return:
241         [K_1,K_2,K_3]
242
243     Note:
244         Reference:
245             IS 800:2007 cl.7.5.1.2
246
247         """
248         if No_of_Bolts_at_Each_End_Connection >= 2:
249             if Connecting_member_Fixity == "Fixed":
250                 K_1 = 0.20
251                 K_2 = 0.35
252                 K_3 = 20
253
254             elif Connecting_member_Fixity == "Hinged":
255                 K_1 = 0.70
256                 K_2 = 0.60
257                 K_3 = 5
258
259         if No_of_Bolts_at_Each_End_Connection == 1:
260             if Connecting_member_Fixity == "Fixed":
261                 K_1 = 0.75
262                 K_2 = 0.35
263                 K_3 = 20
264
265             if Connecting_member_Fixity == "Hinged":

```

```

265         K_1 = 1.25
266         K_2 = 0.50
267         K_3 = 60
268
269     return [K_1,K_2,K_3]
270
271 #cl.7.5.1.2.Design strength of angle strut loaded through one leg
272 @staticmethod
273 def
274     cl_7_5_1_2_Calculation_of_design_strength_of_single_angle_strut_loaded_through_one_leg
275     (L, b_1, b_2, f_y, r_vv, t, E,K_list):
276         """
277             Calculation of design strength of single angle strut loaded
278             through one leg
279
280         Args:
281             L - Length of Angle section in mm
282             b_1,b_2 - width of legs of angle section in mm
283             f_y - yield stress in N/mm**2
284             r_vv - radius of gyration about minor axis in mm
285             t - thickness of the leg in mm
286             E - Young's Modulus of elasticity in N/mm***2
287             epsilon - yield stress ratio
288
289         Return:
290             f_cd - Design compressive strength of the section
291
292         Note:
293             Reference:
294                 IS 800:2007    cl.7.5.1.2
295
296             """
297
298     [K_1,K_2,K_3] = K_list
299
300     alpha = 0.49 #according to ammendment 1
301
302     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
303     epsilon = math.sqrt(250 / f_y)
304
305     lambda_vv = (L / r_vv) / (epsilon * math.sqrt(math.pi ** 2 * E /
306     250))
307
308     lambda_phi = (b_1 + b_2) / (2 * t * epsilon * math.sqrt(math.pi *
309     math.pi * E / 250))
310
311     lambda_e = math.sqrt(K_1 + (K_2 * lambda_vv ** 2) + (K_3 *
312     lambda_phi ** 2))
313
314     phi = 0.5 * (1 + alpha * (lambda_e - 0.2) + lambda_e ** 2)
315     f_cd = min(f_y / (gamma_m0 * (phi + math.sqrt(phi ** phi - lambda_e
316     ** 2))), f_y / gamma_m0)
317
318     return f_cd
319
320 #cl7.6 Laced column
321 #cl 7.6.1.5.Effective slenderness ratigion of lacing member
322 @staticmethod
323 def effective_slenderness_ratio_of_lacing_member(K_L, r_min):
324
325         """
326             Calculation of Effective slenderness ratio of lacing member
327             to account for shear deformation

```

```

319     Args:
320         K_L - effective length of column in mm
321         r_min - radius of gyration of column member in mm
322         SR_0 - actual maximum slenderness ration of column
323     Returns:
324         SR_eff - effective slenderness ratio of lacing
325     Note:
326         Reference:
327             IS 800:2007 cl 7.6.1.5
328         """
329
330         SR_0 = K_L/r_min
331         SR_eff = 1.05*SR_0
332         return SR_eff
333
334     #cl 7.6.2 Width of Lacing Bars
335     @staticmethod
336     def cl_7_6_2_width_of_lacing_bars(d):
337         """
338             Calculation of min width of Lacing Bars
339             Args:
340                 d - nominal bolt/rivet diameter
341             Returns:
342                 w_min - min Width of Lacing Bars
343             Note:
344                 Reference:
345                 IS 800:2007, cl 7.6.2
346             """
347
348         w_min = 3*d
349         return w_min
350
351     #cl 7.6.3 Thickness of Lacing Bars
352     @staticmethod
353     def cl_7_6_3_minimum_thickness_of_lacing_bars(lacing_type,L_eff):
354         """
355             Calculation of min Thickness of Lacing Bars
356             Args:
357                 Lacing_type - either 'single_lacing' or 'double_lacing'
358                 L_eff - effective length of lacing bars
359             Returns:
360                 t_min - minimum thickness of Lacing Bars
361             Note:
362                 Reference:
363                 IS 800:2007, cl 7.6.3
364             """
365         if lacing_type == 'single_lacing':
366             t_min = 1/40 *L_eff
367
368         else:
369             t_min = 1 / 60 * L_eff
370
371         return t_min
372
373     #Cl7.6.6 Design of lacing
374     #7.6.6.1 Transverse shear in the lacing bar
375     @staticmethod
376     def cl_7_6_6_1_transverse_shear_in_the_lacing_bar(P):
377         """
378             Calculation of Transverse shear in the lacing bar
379             Args:

```

```

380         P - axial load on column in N
381     Returns:
382         V_t_min - minimum design transverse shear in N
383     Note:
384         Reference:
385         IS 800:2007 cl 7.6.6.1
386         """
387         V_t_min = 2.5/100 * P
388
389         return V_t_min
390
391
392     # cl7.7 Batten plate
393     # cl7.7.1.4 effective slenderness ratio of batten plate
394     @staticmethod
395     def Cl_7_7_1_4_effective_slenderness_ratio_of_batten_plate(K_L,r_min):
396         """
397         Calculation of effective slenderness ratio
398         Args:
399             K_L -effective length of column in mm
400             r_min - minimum radius of gyration(r_x,r_y,r_z) of column
401             member in mm
402         Returns:
403             SR_eff - effective slenderness ratio of lacing
404         Note:
405             Reference:
406             IS 800:2007, cl 7.6.1.5
407             """
408             SR_eff = 1.1 * (K_L / r_min)
409             return SR_eff
410
411     # Design of Battens
412     # Battens
413     @staticmethod
414     def
415         cl_7_7_2_1_longitudinal_shear_transverse_shear_and_moment_at_connection
416         (P, S, C, N):
417             """
418                 Calculation of longitudinal shear, transverse shear and moment
419                 at connection
420                 Args:
421                     P - total axial force on column in N
422                     S - minimum transverse distance between the centroid of the
423                     rivet/bolt
424                     group/welding connecting the batten to the main member
425                     in mm
426                     N -number of parallel planes of battens
427                     C - distance between centre -to- centre of battens in mm
428             Returns:
429                 V_t - transverse shear force in N
430                 V_b - longitudinal shear force along column axis in N
431                 M - moment at connection in N*mm
432             Note:
433                 Reference:
434                 IS 800:2007, cl.7.7.2.1
435                 """
436
437                 V_t = 2.5 / 100 * P
438                 V_b = V_t * C / (N * S)
439                 M = V_t * C / (N * 2)

```

```
435     return (V_t, V_b, M)
436 #-----
```

## Appendix C

# Python Code for Section 8 IS: 800 2007

```
1  #
2  =====
3 import math
4 # Table 5 Partial Safety Factors for Materials, gamma_m (dict)
5 class IS800_2007(object):
6     cl_5_4_1_Table_5 = {"gamma_m0": {'yielding': 1.10, 'buckling': 1.10},
7                          "gamma_m1": {'ultimate_stress': 1.25},
8                          "gamma_mf": {'shop': 1.25, 'field': 1.25},
9                          "gamma_mb": {'shop': 1.25, 'field': 1.25},
10                         "gamma_mr": {'shop': 1.25, 'field': 1.25},
11                         "gamma_mw": {'shop': 1.25, 'field': 1.50}}
12
13     """      SECTION  8      DESIGN OF MEMBERS SUBJECTED TO BENDING      """
14     # -----
15     # DESIGN OF MEMBER SUBJECTED TO BENDING
16
17     # cl 8.3.3 Effective length for cantilever Beam
18     @staticmethod
19     def cl_8_3_3_Table_16_Effective_length_for_cantilever_beam(L,
20                      Restraint_Condition_1, Restraint_Condition_2,
21                      Loading_condition):
22         """
23             Calculate effective length for cantilever beam of projecting
24             length L as per cl.8.3.3
25
26             Args:
27                 L - Projecting Length of cantilever beam in mm (float)
28
29             Args:
30                 L - Projecting Length of cantilever beam in mm (float)
31                 D - Overall depth of he beam in mm (float)
32
33                 Restrained_condition - Either "At support" or "At Top"
34                 Restraint_Condition_1 - "At support"
35                 Restraint_Condition_2 - "At Top"
36
37                 At_support - Either "Continuous, with lateral restraint to
38                             top"
39                               or "Continuous, with partial torsional
```

```

    restraint"
37                      or "Continuous, with lateral and torsional
    restraint "
38                      or "Restrained laterally,torsionally and
against rotation on plan "
39
        At_top - Either "Free"
40                      or "Lateral restraint to top flange"
41                      or "Torsional restraint"
42                      or "Lateral and torsional restraint"
43
        Loading_condition - Either "Normal" or "Destabilizing"
44
45
46
47     Returns:
48     L_LT =
49
50     cl_8_3_3_Table_16_Effective_length_for_cantilever_beam
51     Note:
52     References:
53     IS800:2007, Table 16 (cl 8.3.3)
54     """
55
56
57     if Restraint_Condition_1 == "Continuous, with lateral restraint to
top flage":
58         if Restraint_Condition_2 == "Free":
59             if Loading_condition == "Normal":
60                 return 3.0 * L
61             else:
62                 return 7.5 * L
63         if Restraint_Condition_2 == "Lateral restraint to top flage":
64             if Loading_condition == "Normal":
65                 return 2.7 * L
66             else:
67                 return 7.5 * L
68         if Restraint_Condition_2 == "Torsional restraint":
69             if Loading_condition == "Normal":
70                 return 2.4 * L
71             else:
72                 return 4.5 * L
73         if Restraint_Condition_2 == "Lateral and Torsional restraint":
74             if Loading_condition == "Normal":
75                 return 2.1 * L
76             else:
77                 return 3.6 * L
78     if Restraint_Condition_1 == "Continuous,with partial torsional
restraint":
79         if Restraint_Condition_2 == "Free":
80             if Loading_condition == "Normal":
81                 return 2.0 * L
82             else:
83                 return 5.0 * L
84         if Restraint_Condition_2 == "Lateral restraint to top flange":
85             if Loading_condition == "Normal":
86                 return 1.8 * L
87             else:
88                 return 5.0 * L
89         if Restraint_Condition_2 == "Torsional restraint":
90             if Loading_condition == "Normal":
91                 return 1.6 * L
92             else:
93                 return 3.0 * L
94     if Restraint_Condition_2 == "Lateral and Torsional restraint":
```

```

92         if Loading_condition == "Normal":
93             return 1.4 * L
94         else:
95             return 2.4 * L
96     if Restraint_Condition_1 == "Continuous,with lateral and torsional
97     restraint":
98         if Restraint_Condition_2 == "Free":
99             if Loading_condition == "Normal":
100                 return 1.0 * L
101             else:
102                 return 2.5 * L
103     if Restraint_Condition_2 == "Lateral restraint to top flage":
104         if Loading_condition == "Normal":
105             return 0.9 * L
106         else:
107             return 2.5 * L
108     if Restraint_Condition_2 == "Torsional restraint":
109         if Loading_condition == "Normal":
110             return 0.8 * L
111         else:
112             return 1.5 * L
113     if Restraint_Condition_2 == "Lateral and Torsional restraint":
114         if Loading_condition == "Normal":
115             return 0.7 * L
116         else:
117             return 1.2 * L
118     if Restraint_Condition_1 == "Restrained laterally,torsionally and
119     against rotation on plan":
120         if Restraint_Condition_2 == "Free":
121             if Loading_condition == "Normal":
122                 return 0.8 * L
123             else:
124                 return 1.4 * L
125     if Restraint_Condition_2 == "Lateral restraint to top flage":
126         if Loading_condition == "Normal":
127             return 0.7 * L
128         else:
129             return 1.4 * L
130     if Restraint_Condition_2 == "Torsional restraint":
131         if Loading_condition == "Normal":
132             return 0.6 * L
133         else:
134             return 0.6 * L
135     if Restraint_Condition_2 == "Lateral and Torsional restraint":
136         if Loading_condition == "Normal":
137             return 0.5 * L
138         else:
139             return 0.5 * L
140
141     @staticmethod
142     def cl_8_3_1_Table_15_Effective_length_for_simply_supported_beams(L,D,
143     Restraint_Condition_1 ,
144     Restraint_Condition_2 , Loading_Condition):
145         """
146             Calculate effective length against lateral torsional buckling
for simply supported Beams and girders
                where no lateral restraint to the compression flange is
provided as per cl.8.3.1
146

```

```

147     Args:
148         L - Span of simply supported beams and girders in mm (float)
149         D - Overall depth of the beam in mm (float)
150
151         Restraint_Condition - Either "Torsional Restraint" or "Warping Restraint"
152             Restraint_Condition_1 - "Torsional Restraint"
153             Restraint_Condition_2 - "Warping Restraint"
154
155         "Torsional Restrained" - Either "Fully restrained" or
156                             "Partially restrained by bottom flange support connection" or
157                             "Partially restrained by bottom flange bearing support"
158
159         "Warping_Restraint" - Either "Both flanges fully restrained"
160     " or
161         "Both flanges partially restrained" or
162         "Compression flange fully restrained"
163     or
164         "Compression flange partially restrained" or
165         "Warping not restrained in both flange"
166
167     Returns:
168         L_LT - cl_8_3_1_Effective length for simply supported Beams in mm (float)
169
170     Note:
171         References:
172             IS800:2007, Table 15 (cl 8.3.1)
173             """
174
175     if Restraint_Condition_1 == "Fully Restrained":
176         if Restraint_Condition_2 == "Both flanges partially restrained":
177             :
178                 if Loading_Condition == "Normal":
179                     return 0.70 * L
180                 else:
181                     return 0.85 * L
182             if Restraint_Condition_2 == "Compression flange fully Restrained":
183                 if Loading_Condition == "Normal":
184                     return 0.75 * L
185                 else:
186                     return 0.90 * L
187             if Restraint_Condition_2 == "Both flanges fully restrained":
188                 if Loading_Condition == "Normal":
189                     return 0.80 * L
190                 else:
191                     return 0.95 * L
192             if Restraint_Condition_2 == "Compression flange partially Restrained":
193                 if Loading_Condition == "Normal":
194                     return 0.85 * L
195                 else:
196                     return 1.00 * L

```

```

196         if Restraint_Condition_2 == "Warping not restrained in both
197             flanges":
198                 if Loading_Condition == "Normal":
199                     return 1.00 * L
200                 else:
201                     return 1.20 * L
202             if Restraint_Condition_1 == "Partially restrained by bottom flange
203                 support connection":
204                     if Restraint_Condition_2 == "Warping not restrained in both
205                         flanges":
206                             if Loading_Condition == "Normal":
207                                 return 1.00 * L + 2 * D
208                             else:
209                                 return 1.20 * L + 2 * D
210             if Restraint_Condition_1 == "Partially restrained by bottom flange
211                 bearing support":
212                     if Restraint_Condition_2 == "Warping not restrained in both
213                         flanges":
214                             if Loading_Condition == "Normal":
215                                 return 1.2 * L + 2 * D
216                             else:
217                                 return 1.4 * L + 2 * D
218
219
220     @staticmethod
221     def cl_8_3_Effective_length_against_torsional_restraint(L, D, Beam_type,
222 , Restraint_Condition_1,
223
224     Restraint_Condition_2 ,
225
226     Loading_Condition):
227         """
228             Calculation of effective length for given type of beam type as
229             per cl.8.3
230
231     Args:
232
233         L - Span of simply supported beams and girders in mm (float)
234     for
235         "
236             Simply_supported_with_no_lateral_restrained_to_the_compression_flanges
237             ",
238                 Projecting Length of cantilever beam in mm (float) for
239                 "Cantilever_beam",
240                 Length of relevant segment between the lateral restraint
241             in mm (float) for
242                 "Simply_supported_with_intermediate_lateral_restraints",
243                 Centre-to-centre distance of the restraint member in mm (
244             float) for
245                 'Beam provided with members to give effective lateral
246             restraint to compression flange at interval'
247
248                 Beam_type - Either "
249             Simply_supported_with_no_lateral_restrained_to_the_compression_flanges"
250                 or "
251             Simply_supported_with_intermediate_lateral_restraints"
252                 or "
253             Beam_provided_with_members_to_give_effective_lateral_restrain_to_compression_flange_at_
254             "
255                 or "Cantilever_beam"

```

```

238     FOR "
239     Simply_supported_with_no_lateral_restrained_to_the_compression_flanges"
240         Restraint_Condition - Either "Torsional Restraint" or "warping
241             Restraint"
242
243             Restraint_Condition - Either "Torsional Restraint" or "Warping
244             Restraint"
245
246             Restraint_Condition_1- "Torsional Restraint"
247             Restraint_Condition_2- "Warping Restraint"
248
249
250             "Torsional Restrained" - Either "Fully restrained" or
251                 "Partially restrained by bottom
252                     flange support connection" or
253                         "Partially restrained by bottom
254                             flange bearing support"
255
256             "Warping_Restraint" - Either "Both flange fully restrained" or
257                 "Compression flange fully restrained"
258             or
259                 "Compression flange partially
260             restrained" or
261                 "Warping not restrained in both flange
262             "
263
264
265     FOR "Cantilever_beam":
266
267         Restrained_condition - Either "At support" or "At Top" for "
268             Cantilever_beam"
269
270             Restraint_Condition_1- "At support"
271             Restraint_Condition_2- "At Top"
272
273             At_support - Either "Continuous, with lateral restraint to top
274             "
275                 or "Continuous, with partial torsional
276                     restraint"
277                 or "Continuous, with lateral and torsional
278                     restraint"
279                 or "Restrained laterally,torsionally and
280                     against rotation on plan "
281
282             At_top - Either "free"
283                 or "lateral restraint to top flange"
284                 or "Torsional restraint"
285                 or "Lateral and torsional restraint"
286
287             Loading_condition - Either "Normal" or "Destabilizing"
288
289
290     Returns :
291         L_LT - effective_length_of_beam in mm (float)
292
293     Note:
294         References:
295             IS800:2007, cl 8.3.
296
297         """
298
299
300
301
302
303
304
305
306
307
308
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310
311
312
313
314
315
316
317
318
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286     if Beam_type == "Simply_supported_with_no_lateral_restrained_to_the_compression_flanges":
287         :
288             L_LT = IS800_2007.
289             cl_8_3_1_Table_15_Effective_length_for_simply_supported_beams(L, D,
290             Restraint_Condition_1,
291             Restraint_Condition_2,
292             Loading_Condition)
293     elif Beam_type == 'Simply supported with intermediate lateral
294     restraints':
295         L_LT = 1.2 * L
296
297     elif Beam_type == "Beam_provided_with_members_to_give_effective_lateral_restrain_to_compression_flange_at_"
298     " ":
299         L_LT = 1.2 * L #TODO:doubt-check
300     else:
301         L_LT = IS800_2007.
302     cl_8_3_3_Table_16_Efective_length_for_cantilever_beam(L,
303     Restraint_Condition_1,
304
305     Restraint_Condition_2, Loading_Condition)
306
307     return L_LT
308
309
310     # Design Strength in Bending(Flexure)
311     @staticmethod
312     def cl_8_2_Design_strength_in_bending(M, M_d):
313         """ Calculation of design bending strength
314         Args:
315             M: Factored design moment in N*mm
316             M_d: design bending strength of the section in N*mm
317         Return:
318             M_d - design bending strength of the section in N*mm
319         Note:
320             References:
321                 IS800:2007, cl 8.2.
322             """
323
324
325     return bool(M <= M_d)
326
327
328     @staticmethod
329     def cl_8_2_Design_bending_strength_of_laterally_unsupported_beam(z_p,
330     z_e, f_y, v, v_d, m_dv, plastic=False,
331                                         compact=False
332     ):
333         """Calculation of bending strength of laterally unsupported beam
334         for low shear and high shear case
335         Args:
336             beta_b - 1 for plastic and compact
337                     Z_e/Z_p for semi-compact
338             z_e - Elastic section modulus of the cross section in mm**3
339             z_p - Plastic section modulus of the cross section in mm**3
340             f_y - yield stress of the material (in N/ mm**2 )
341             v - Factored design shear strength in N
342             v_d - Design shear strength in N
343             m_dv - Design bending strength under high shear as defined
344             in Cl 9.2 in N*m

```

```

331         plastic - True if beam is plastic else False
332         compact - True for compact section else False
333
334     Returns:
335         m_d - Design Bending strength in N*m
336     Note:
337         References:
338             IS800:2007, cl 8.2.1.2, cl. 8.2.1.3
339
340     """
341     beta_b = z_e / z_p #semi-compact section
342     if plastic is True:
343         beta_b = 1
344     if compact is True:
345         beta_b = 1
346     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
347     if v <= 0.6 * v_d:
348         m_d = beta_b * z_p * f_y / gamma_m0
349
350     if v > 0.6 * v_d:
351         m_d = m_dv
352
353     return m_d
354
355 # c18.2.2 DESIGN BENDING STRENGTH OF LATERALLY UNSUPPORTED BEAMS
356 # c18.2.2.1 Elastic lateral torsional buckling moment
357 @staticmethod
358 def
359     cl_8_2_2_1_Elastic_lateral_torsional_buckling_moment_doubly_symmetric(
360         I_t, I_w, I_y, E, G, L_LT):
361         """
362             Calculation of elastic critical moment of lateral torsional
363             buckling for simply supported, prismatic members
364             with symmetric c/s
365             Args:
366
367                 I_t - torsional constant
368                 I_w - warping constant
369                 I_y - moment of inertia about weaker axis
370                 E - Young's Modulus of Elasticity
371                 G - modulus of rigidity
372                 L_LT - effective length for lateral torsional buckling
373             Return:
374                 M_cr - Elastic lateral torsional buckling moment in N*mm
375             Notes:
376                 Reference:
377                     IS 800:2007, cl. 8.2.2.1.
378
379             """
380
381         M_cr = math.sqrt((math.pi ** 2 * E * I_y / L_LT ** 2) * (G * I_t +
382                         math.pi ** 2 * E * I_w / L_LT ** 2))
383
384         return M_cr
385
386     @staticmethod
387     def cl_8_2_2_design_bending_strength_of_laterally_unsupported_beam(Z_p,
388         Z_e, L_LT, f_y, I_y, I_t, I_w, E, G, section, plastic=False, compact=
389         False):

```

```

386 """
387     Calculation of design bending strength of laterally
388     unsupported beam
389     Args:
390         Z_p - plastic section modulus with respect to extreme
391         compression fibre
392         Z_e - elastic section modulud with respect to extreme
393         compression fibre
394         L_LT - effective length for lateral torsional buckling
395         I_y - moment of inertia about minor axis of c/s
396         f_y - yield stress
397         I_t - torsional constant
398         I_w - warping constant
399         E - modulus of elasticity
400         G - modulus of rigidity
401         plastic - boolean True if section is plastic
402         compact - boolean True if section is compact
403         section - Either 'Rolled_steel_section' or "
404             Welded_steel_section'
405
406     Returns:
407         M_d - Design bending strength of laterally unsupported beam
408         in N*mm
409
410     Note:
411         Reference:
412             IS 800:2007, cl. 8.2.2.
413
414     """
415
416     beta_b = Z_p / Z_e
417     if plastic is True:
418         beta_b = 1
419     if compact is True:
420         beta_b = 1
421
422     if section == 'Rolled_steel_section':
423         alpha_LT = 0.21
424     elif section == 'Welded_steel_Connection':
425         alpha_LT = 0.49
426
427     M_cr = IS800_2007.
428     cl_8_2_2_1_Elastic_lateral_torsional_buckling_moment_doubly_symmetric(
429         I_t, I_w, I_y, E, G, L_LT)
430     f_cr_b = M_cr / (beta_b * Z_p)
431     Lambda_LT = min(math.sqrt(f_y / f_cr_b), math.sqrt(1.2 * Z_e * f_y
432     / M_cr))
433     phi_LT = 0.5 * (1 + alpha_LT * (Lambda_LT - 0.2) + Lambda_LT ** 2)
434     X_LT = min(1.0, 1 / (phi_LT + math.sqrt(phi_LT ** 2 - Lambda_LT ** 2)))
435
436     if Lambda_LT < 0.4:
437         X_LT = 1
438
439     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
440
441     f_bd = X_LT * f_y / gamma_m0
442
443     M_d = beta_b * Z_p * f_bd

```

```

438     return M_d
439
440
441     # cl8.4 Shear Design
442     @staticmethod
443     def cl_8_4_design_shear_strength_of_beam(V_n):
444         """
445             Design shear strength
446         Args:
447             V_n - Nominal shear strength of a cross-section
448         Returns:
449             V_d - Design shear strength in N
450         Note:
451             Reference:
452             IS 800:2007, cl. 8.4
453
454         """
455
456         gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
457         V_d = V_n / gamma_m0
458         return V_d
459
460
461     @staticmethod
462     def cl_8_4_1_nominal_plastic_shear_resistance_under_pure_shear(A_v,
463     f_yw):
464         """
465             Calculation of nominal plastic shear resistance under pure
466             shear
467
468             Args:
469                 A_v - Shear area
470                 f_yw - yield shear of the web
471             Returns:
472                 V_n - Nominal plastic shear resistance under pure shear
473             Note:
474                 Reference:
475                 IS 800:2007, cl. 8.4.1
476
477             V_n = A_v * f_yw / math.sqrt(3)
478             return V_n
479
480
481
482     def cl_8_4_1_1_shear_area_of_different_section(A, b, d, h, t_f, t_w,
483     section, Axis_of_Bending, load_application_axis,
484                                         cross_section):
485
486         """
487             Calculation of shear area of different section
488
489             Args:
490                 A - cross section area in mm**2
491                 b - overall breadth of tubular section,breadth of I -
492                     section flange in mm
493                 d - clear depth of the web between flange in mm
494                 h - overall depth of the section in mm
495                 t_f - thickness of the flange in mm
496                 t_w - thickness of the web in mm
497                 section - Either 'I section ' and 'Channel Section' or '

```

```

        Rectangular hollow section of uniform depth'
495           or 'Circular hollow tubes of uniform thickness' or
496           'plates' or 'solid bars'
497               Load_application_axis - Either 'Loaded parallel to depth'
498           or 'Loaded parallel to width(b)'
499               Axis_of_Bending - Either 'Major Axis Bending' or 'Minor
500           Axis Bending'
501               cross_section - Either 'Hot Rolled' or 'Welded'

502       Return:
503           A_v - Shear area in mm*mm

504       Note:
505           Reference:
506           IS 800:2007, cl. 8.4.1.1

507       """
508
509     if section == 'I section' or section == 'Channel Section':
510         if Axis_of_Bending == 'Major Axis Bending':
511             if cross_section == 'Hot-Rolled':
512                 A_v = h * t_w
513             else:
514                 A_v = d * t_w
515         return A_v

516
517     if Axis_of_Bending == 'Minor Axis Bending':
518         if cross_section == 'Hot-Rolled' or cross_section == 'Welded':
519             A_v = 2 * b * t_f
520         return A_v
521     if section == 'Rectangular hollow section of uniform depth':
522         if load_application_axis == 'Loaded parallel to depth':
523             A_v = A * h / (b + h)
524         else:
525             A_v = A * b / (b + h)
526         return A_v

527
528     if section == 'Circular hollow tubes of uniform thickness':
529         A_v = A
530         return A_v

531
532     if section == 'plates' or section == 'solid':
533         A_v = A
534         return A_v

535
536
537 # c18.4.2 TODO: CHECK RESISTANCE TO SHEAR BUCKLING
538 # c18.4.2.1 Check for resistance to shear buckling
539 @staticmethod
540 def cl_8_4_2_shear_buckling_check(d, t_w, k_v, fy, stiffeners):
541     """
542         Check for resistance against shear buckling
543         Args:
544             d - clear depth of web between flanges
545             t_w - thickness of web
546             k_v - shear buckling coefficient
547             fy - yield stress in N/mm^2
548             stiffeners - True if web has stiffeners else False
549         Return:
550             check - True if check is satisfied else false
551         Note:

```

```

552             Reference:  

553                 IS 800:2007, cl. 8.4.2.1  

554             """  

555             epsilon = math.sqrt(250/fy)  

556             if not stiffeners:  

557                 val = 67 * epsilon  

558             else:  

559                 val = 67 * epsilon * math.sqrt(k_v/5.35)  

560             if d / t_w > val :  

561                 check = True  

562             else:  

563                 check = False  

564  

565             return check  

566  

567 # cl8.4.2.2 Shear buckling design method  

568 @staticmethod  

569 def cl_8_4_shear_buckling_coeff_Kv(only_at_support, c=None, d=None):  

570     """  

571     Args:  

572         only_at_support - True if transverse stiffeners are provided  

573         only at support  

574             else False  

575         c - spacing of transverse stiffeners  

576         d - depth of web  

577     Returns:  

578         k_v - shear buckling coefficient  

579     Note:  

580         Reference - IS800_2007 cl.8.4.2.1 and cl.8.4.2.2  

581         """  

582         if only_at_support:  

583             k_v = 5.35  

584         elif c / d < 1:  

585             k_v = 4 + 5.35 / (c / d) ** 2  

586         else:  

587             k_v = 5.35 + 4 / (c / d) ** 2  

588         return k_v  

589  

590     @staticmethod  

591     def cl_8_4_2_2_nominal_shear_post_critical(A_v,k_v,mu,E,d,t_w,f_yw):  

592         """  

593             Calculates nominal shear strength as governed by buckling using  

594             simple post critical method  

595             Args:  

596                 A_v - shear area defined in cl 8.4.1.1  

597                 k_v - shear buckling coefficient  

598                 mu - poisson's ratio  

599                 E - modulus of elasticity  

600                 d - depth of web  

601                 t_w - thickness of web  

602                 f_yw - characteristic yield stress of web material  

603             Return:  

604                 V_n - nominal shear strength  

605             Note:  

606                 Reference: IS800:2007 cl.8.4.2.2  

607                 """  

608                 T_cr_c = (k_v * math.pi ** 2 * E) / (12 * (1 - mu ** 2) * (d / t_w)  

609                 ** 2)  

610                 lambda_w = math.sqrt(f_yw / (math.sqrt(3) * T_cr_c))

```

```

610     if lambda_w < 0.8:
611         T_b = (f_yw / math.sqrt(3))
612     elif 0.8 < lambda_w < 1.2:
613         T_b = (1 - 0.8 * max((lambda_w - 0.8), 0)) * (f_yw / math.sqrt
614 (3))
615     else:
616         T_b = f_yw / (math.sqrt(3) * lambda_w ** 2)
617
618     V_cr = A_v * T_b
619     V_n = V_cr
620     return V_n
621
622     @staticmethod
623     def cl_8_4_2_2_nominal_shear_tension_field(A_v, d, t_w, t_f, b_f, f_yw, c,
624 f_yf, N_f):
625         """
626             Calculates nominal shear strength as governed by buckling using
627             tension field method
628
629             Args:
630                 A_v - shear area defined in cl 8.4.1.1
631                 k_v - shear buckling coefficient
632                 mu - poisson's ratio
633                 E - modulus of elasticity
634                 d - depth of web
635                 t_w - thickness of web
636                 t_f - thickness of flange
637                 b_f - width of flange
638                 f_yw - characteristic yield stress of web material
639                 c - spacing of stiffeners in web
640                 f_yf - characteristic yield stress of flange material
641                 N_f - axial force in flange due to overall bending and
642                     external axial force
643
644             Return:
645                 Note: Reference - IS800:2007 cl.8.4.2.2
646
647             if c/d < 1.0:
648                 return 'error : c/d must be greater than or equal to 1'
649
650             phi = math.atan(d / c) / 1.5
651             psi = 1.5 * T_b * math.sin(2 * phi)
652
653             gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
654             M_fr = 0.25 * b_f * t_f ** 2 * f_yf * (1 - (N_f / (b_f * t_f * f_yf
655 / gamma_m0)) ** 2)
656
656             s = min(c, (2 / math.sin(phi)) * math.sqrt(M_fr / f_yw * t_w)))
657             s_c = s
658             s_t = s
659             w_tf = d * math.cos(phi) - (c - s_c - s_t) * math.sin(phi)
660             f_v = math.sqrt(f_yw ** 2 - 3 * T_b ** 2 + psi ** 2) - psi
661             V_p = A_v * f_yw / math.sqrt(3)
662             V_tf = min(V_p, (A_v * T_b + 0.9 * w_tf * t_w * f_v * math.sin(phi
663 )))
664             V_tf = V_n
665             return V_n
666
667
668             # Stiffened web Panels
669             # End plate Design
670             # cl8.5.3 Anchor forces

```

```

665     @staticmethod
666     def cl_8_5_3_anchor_forces(d, t, f_y, V, V_cr, V_tf):
667         """ Calculation of resultant longitudinal shear and moment
668         Args:
669             d - web depth in mm
670             t - thickness of the section in mm
671             f_y - yield stress in N/mm**2
672             V_cr - critical shear strength as defined in cl8.4.2.2.
673             V_tf - basic shear strength as defined in cl8.4.2.2.
674
675             V - actual factored shear force
676         Returns:
677             M_tf - resultant longitudinal moment in N*mm
678             R_tf - resultant longitudinal shear in N*mm
679
680         Note:
681             Reference:
682                 IS 800:2007, cl. 8.5.3
683         """
684
685     V_p = d * t * f_y / math.sqrt(3)
686
687     H_q = 1.25 * V_p * math.sqrt(1 - V_cr / V_p)
688
689     if V < V_tf:
690         H_q *= (V - V_cr) / (V_tf - V_cr)
691
692     R_tf = H_q / 2
693     M_tf = H_q * d / 10
694
695     return (R_tf, M_tf)
696
697
698 # cl8.6 Design of Beams and Plate Girders with Solid Webs
699 # cl8.6.1 Minimum Web Thickness
700 # cl8.6.1.1 Serviceability requirement
701 @staticmethod
702 def cl_8_6_1_1_minimum_web_thickness(d, t_w, c, f_yw,
703 serviceability_requirement, web_connection_to_flange):
704     """
705         Checking the serviceability requirement of minimum thickness
706         of web
707         Args:
708             d - web depth in mm
709             t_w - thickness of web in mm
710             c - spacing of transverse stiffener in mm
711             epsilon_w - yield stress ratio of web
712             f_yw - yield stress of the web in N/mm**2
713             serviceability_requirement - ,
714             transverse_stiffener_not_provided',
715             ,
716             only_transverse_stiffeners_provided_in_web_flange_connection_along_both_longitudinal_edges',
717             ,
718             transverse_and_longitudinal_stiffener_at_one_level_as_cl_8_7_13',
719             ,
720             second_longitudinal_stiffener_provided_at_NA'
721             web_connection_to_flange - 'along_both_longitudinal_edges',
722             'along_one_longitudinal_edge'
723     >
724         Returns:

```

```

719             True, if safety condition is satisfied else False
720
721     Note:
722         Reference:
723             IS 800:2007, cl. 8.6.1.1
724
725     """
726     epsilon_w = math.sqrt(250 / f_yw)
727
728     if serviceability_requirement == 'transverse_stiffener_not_provided':
729         if web_connection_to_flange == 'along_both_longitudinal_edges':
730             return d/t_w <= 200 * epsilon_w
731         elif web_connection_to_flange == 'along_one_longitudinal_edge':
732             return d/t_w <= 90 * epsilon_w
733     elif serviceability_requirement == 'only_transverse_stiffeners_provided_in_web_flange_connection_along_both_longitudinal_edges':
734         if 3 * d >= c >= d:
735             return d / t_w <= 200 * epsilon_w
736         elif 0.74 * d <= c < d:
737             return c / t_w <= 200 * epsilon_w
738         elif c < 0.74 * d:
739             return d / t_w <= 270 * epsilon_w
740     else:
741         return 'web_is_unstiffened'
742
743     elif serviceability_requirement == 'transverse_and_longitudinal_stiffener_at_one_level_as_cl_8_7_13':
744         if d < c <= 2.4 * d:
745             return bool(d / t_w <= 250 * epsilon_w)
746         elif 0.74 * d <= c < d:
747             return bool(c / t_w <= 250 * epsilon_w)
748         else:
749             return bool(d / t_w <= 340 * epsilon_w)
750
751     else:
752         return bool(d / t_w <= 400 * epsilon_w)
753
754 # cl 8.6.1.2 Compression flange buckling requirement
755 def cl_8_6_1_2_web_thickness_to_avoid_buckling_of_compression_flange(d,
756                         t_w, c, f_yf, Transverse_stiffener):
757     """
758         Check for minimum web thickness to avoid buckling of
759         compression flange
760
761     Args:
762         d - depth of the web in mm
763         t_w - thickness of the web in mm
764         c - spacing of transverse stiffener in mm
765         epsilon_f - yield stress ratio of flange
766         f_yw - yield stress of compression flange in N/mm**2
767         Transverse_stiffener - either 'provided' or 'not provided'
768
769     Return:
770         True or False
771
772     Note:
773         Reference:
774             IS 800:2007, cl. 8.6.1.1
775
776     """
777     epsilon_f = math.sqrt(250 / f_yf)
778     if Transverse_stiffener == 'not provided':
779         return bool(d / t_w <= 345 * epsilon_f ** 2)

```

```

774     else:
775         if c >= 1.5 * d:
776             return bool(d / t_w <= 345 * epsilon_f ** 2)
777         else:
778             return bool(d / t_w <= 345 * epsilon_f)
779
780 # cl8.7.1.5 Buckling resistance of stiffeners
781 # Effective length for load carrying web stiffeners
782 @staticmethod
783 def cl_8_7_1_5_effective_length_for_load_carrying_web_stiffeners(L,
restrained_condition):
784     """
785         Calculation of Effective length for load carrying web
stiffeners for calculating
786         buckling resistance F_xd
787         Args:
788             L - length of stiffener in mm
789             restrained_condition - Either ,
flange_restrained_against_rotation' or
790                             'flange_not_restrained_against_rotation
,
791         Returns:
792             K_L - effective length for load carrying web stiffeners in
mm
793         Note:
794             Reference:
795                 IS 800:2007 ,    cl 8.7.1.5
796             """
797
798
799     if restrained:
800         K_L = 0.7 * L
801         return K_L
802     else:
803         K_L = L
804         return K_L
805
806 # Cl 8.7.2.4 Minimum stiffeners
807 @staticmethod
808 def
cl_8_7_2_4_I_s_for_transverse_web_Stiffeners_not_subjected_to_external_load
(c, d, t_w):
809     """
810         Calculation of second moment of area when transverse web
stiffener
811             not subjected to external load
812             Args:
813                 d - depth of thw web in mm
814                 t_w - minimum required web thickness foe spacing using
tension filed action ,as given in cl8.4.2.1 in mm
815                 c - actual stiffener spacing in mm
816             Return:
817                 I_s_min - second moment of area in mm**4
818             Note:
819                 Reference:
820                     IS 800:2007 ,    cl 8.7.2.4
821             """
822     if c / d >= math.sqrt(2):
823         I_s_min = 0.75 * d * t_w ** 3
824     else:
825         I_s_min = 1.5 * d ** 2 * t_w ** 3 / c ** 2

```

```

826     return I_s_min
827
828
829 # cl 8.7.2.5 Buckling check on intermediate transverse web stiffeners
830 def cl_8_7_2_5_buckling_check_on_intermediate_transverse_web_stiffener(
831     V, F_qd, F_x, F_xd, M_q, M_yq, V_cr):
832     """
833         Buckling check on intermediate transverse web stiffeners
834     Args:
835         F_qd - design resistance of the intermediate stiffeners in
836             N
837         V - factored shear force adjacent to the stiffener in N
838         F_qd - design resistance of an intermediate web stiffener
839             to buckling corresponding to buckling about at
840             axis parallel to the web as in cl 8.7.1.5 in N
841         F_x - external load or reaction at the stiffener in N
842         F_xd - design resistance of a load carrying stiffener
843             corresponding to buckling about axis parallel
844             to the web as in cl 8.7.1.5 in N
845         M_q - moment on the stiffener due to eccentrically
846             applied load and transverse load, if any in N*mm
847         M_yq - yield moment capacity of the stiffener based
848             on its elastic modulus about its centroidal
849             axis parallel to the web in N*mm
850
851     Returns:
852         F_q - stiffener force in N
853
854     Note:
855         Reference:
856             IS 800:2007, cl 8.7.2.5, cl.8.7.3
857
858     """
859     gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
860     F_q = min(V - V_cr / gamma_m0, F_qd)
861     if (F_q - F_x) / F_qd + F_x / F_xd + M_q / M_yq <= 1:
862         return F_q
863     else:
864         return 'cl.8.7.2.5.warning:buckling check on intermediate
865             transverse web stiffener not satisfied'
866
867
868
869 # cl 8.7.2.6 Connection of intermediate stiffeners to web
870 @staticmethod
871 def cl_8_7_2_6_shear_between_each_component_of_stiffener_and_web(t_w,
872     b_s, s_e):
873
874     """
875         Calculation of minimum allowable shear between each component
876         of stiffener and web
877     Args:
878         t_w - web thickness in mm
879         b_s - outstanding width of the stiffeners in mm
880
881     Returns:
882         V_is_min - minimum shear between each component of
883             stiffener and web in N/mm
884
885
886     Notes:
887         Reference:
888             IS 800:2007, cl 8.7.2.6

```

```

881
882     """
883     V = t_w ** 2 / 5 * b_s + s_e
884     return V
885
886
887     # cl 8.7.3 Load Carrying stiffeners
888     # cl 8.7.3.1 Web Checking
889     @staticmethod
890     def cl_8_7_3_1_area_of_cross_section_of_web(b_1, n_1, t_w):
891         """
892             Calculation of area of cross section of the web
893             Args:
894                 b_1 - width of stiff bearing on the flange in mm
895                 n_1 - dispersion of the load through the web
896                     45 degree, to the level of half the depth
897                     of the cross section
898                 t_w - web thickness in mm
899                     45 degrees, to the level of half the depth
900                     of the cross section
901             Returns:
902                 A_w - area of cross section of the web in mm**2
903             Notes:
904                 Reference:
905                 IS 800:2007, cl 8.7.3.1
906             """
907             A_w = (b_1 + n_1) / t_w
908             return A_w
909
910     # cl 8.7.4 Bearing Stiffeners
911
912     @staticmethod
913     def cl_8_7_4_force_applied_through_flange_by_loads_(b_1, n_2, t_w, f_yw):
914         """
915             Calculation of force applied through a flange by load or
916             reaction
917             exceeding the local capacity of the web at its connection
918             Args:
919                 b_1 - stiff bearing length in mm
920                 n_2 - length obtained by dispersion through the flange to
921                     the web
922                     junction at a slope of 1:2.5 to the plane of the
923                     flange in mm
924                 t_w - thickness of the web in mm
925                 f_yw - yield stress of the web in N/mm**2
926
927             Returns:
928                 F_w - force applied through flange by loads in N
929
930             Notes:
931                 Reference:
932                 IS 800:2007, cl 8.7.4
933             """
934             gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
935             F_w = (b_1 + n_2) * t_w * f_yw / gamma_m0
936             return F_w
937
938     # cl 8.7.5 Design of load carrying stiffeners

```

```

938     # cl 8.7.5.1 Buckling check
939     # cl 8.7.5.2 Bearing check
940
941     @staticmethod
942     def cl_8_7_5_2_bearing_strength_of_stiffeners(F_x, A_q, f_yq):
943         """
944             Calculation of bearing strength of stiffeners
945
946             Args:
947                 F_x - external load or reaction in N
948                 A_q - area of the stiffeners in contact with the flange in
949                     mm
950                 f_yq - yield stress of the stiffeners in N/mm**2
951
952             Returns:
953                 F_psd - bearing strength of stiffeners in N
954
955             Notes:
956                 Reference:
957                 IS 800:2007, cl 8.7.4
958
959                 gamma_m0 = IS800_2007.cl_5_4_1_Table_5["gamma_m0"]['yielding']
960                 F_psd = max(A_q * f_yq / (0.8 * gamma_m0), F_x)
961                 return F_psd
962
963             # cl 8.7.9 Torsional Stiffeners
964             @staticmethod
965             def cl_8_7_9_minimum_second_moment_of_area_of_the_stiffener_section(D,
966                 T_cf, L_LT, r_y):
967                 """
968                     calculation of minimum second moment of area of the stiffener
969
970                     Args:
971                         D = overall depth of beam at support in mm
972                         T_cf = maximum thickness of compression flange in the span
973                             under consideration in mm
974                         K_L= laterally unsupported effective length of the
975                             compression flange of the beam in mm
976                         r_y = radius of gyration of the beam about the minor axis
977                             in mm
978
979                     Returns:
980                         I_s_min = calculation of minimum second moment of area of
981                             the stiffener in mm**4
982
983
984                     Notes:
985                         Reference:
986                         IS 800:2007, cl 8.7.4
987
988                         if L_LT / r_y <= 50:
989                             alpha_s = 0.006
990                         elif 50 < L_LT / r_y <= 100:
991                             alpha_s = 0.3 / (L_LT / r_y)
992                         else:
993                             alpha_s = 30 / (L_LT / r_y) ** 2
994
995                         I_s_min = 0.34 * alpha_s * D ** 3 * T_cf
996
997                         return I_s_min

```



## Appendix D

# Python Code for Annex E IS: 800 2007

```
1     """      ANNEX   E          ELASTIC LATERAL TORSIONAL BUCKLING      """
2     import math
3     # Table 5 Partial Safety Factors for Materials, gamma_m (dict)
4     class IS800_2007(object):
5         cl_5_4_1_Table_5 = {"gamma_m0": {'yielding': 1.10, 'buckling': 1.10},
6                             "gamma_m1": {'ultimate_stress': 1.25},
7                             "gamma_mf": {'shop': 1.25, 'field': 1.25},
8                             "gamma_mb": {'shop': 1.25, 'field': 1.25},
9                             "gamma_mr": {'shop': 1.25, 'field': 1.25},
10                            "gamma_mw": {'shop': 1.25, 'field': 1.50}}
11
12     # CALCULATION OF EFFECTIVE LENGTH AGAINST LATERAL TORSIONAL BUCKLING.
13     def cl_8_3_1_Effective_length_for_simply_supported_beams(L, D,
14         Restraint_Condition_1, Restraint_Condition_2,
15         Loading_Condition):
16
17         """
18             Calculate effective length against lateral torsional buckling
19             for simply supported Beams and girders
20                 where no lateral restraint to the compression falnge is
21             provided as per cl.8.3.1
22
23             Args:
24                 L - Span of simply suppotred beams and girders in mm (float)
25                 D - Overall depth of he beam in mm (float)
26
27                 Restraint_Condition - Either "Torsional Restraint" or "
28             wraping Restraint"
29                 Restraint_Condition_1 - "Torsional Restraint"
30                 Restraint_Condition_2 - "Warping_Restraint"
31
32                 "Torsional Restrained" - Either "Fully_resrtrained" or
33                         "
34             Partially_restrained_by_bottom_flange_support_condition" or
35                         "
36             Partially_restrained_by_bottom_flange_support_condition"
37
38                 "Warping_Restraint" - Either "Both_flange_fully_restrained"
39             or
40                         "compression_flange_fully_restrained"
```

```

    or
    "Compression_flange_partially_restrained" or
    "Warping_not_restrained_in_both_flange"
"

36
37
38           Loading_Condition - Either "Normal" or "Destabilizing"
39
40
41
42           Returns:
43           L_LT - cl_8_3_1_Effective length for simply supported
44           Beams in mm (float)
45
46           Note:
47           References:
48           IS800:2007, Table 15 (cl 8.3.1)
49
50           """
51
52   if Restraint_Condition_1 == "Fully Restrained":
53       if Restraint_Condition_2 == "Both flanges fully restrained":
54           if Loading_Condition == "Normal":
55               return 0.70 * L
56           else:
57               return 0.85 * L
58       if Restraint_Condition_2 == "Compression flange fully
59       Restrained":
60           if Loading_Condition == "Normal":
61               return 0.75 * L
62           else:
63               return 0.90 * L
64   if Restraint_Condition_2 == "Both flanges partially restrained"
65   :
66       if Loading_Condition == "Normal":
67           return 0.80 * L
68       else:
69           return 0.95 * L
70   if Restraint_Condition_2 == "Compression flange partially
71   Restrained":
72       if Loading_Condition == "Normal":
73           return 0.85 * L
74       else:
75           return 1.00 * L
76   if Restraint_Condition_2 == "Wrapping not restrained in both
77   flanges":
78       if Loading_Condition == "Normal":
79           return 1.00 * L
80       else:
81           return 1.20 * L
82   if Restraint_Condition_1 == "Partially restrained by bottom flange
83   support connection":
84       if Restraint_Condition_2 == "Wrapping not restrained in both
85   flanges":
86           if Loading_Condition == "Normal":
87               return 1.00 * L + 2 * D
88           else:
89               return 1.20 * L + 2 * D
90   if Restraint_Condition_1 == "Partially restrained by bottom flange
91   support connection":
92       if Restraint_Condition_2 == "Wrapping not restrained in both
93   flanges":
94           if Loading_Condition == "Normal":
95               return 1.00 * L + 2 * D
96           else:
97               return 1.20 * L + 2 * D

```

```

bearing support":
85     if Restraint_Condition_2 == "Wrapping not restrained in both
flanges":
86         if Loading_Condition == "Normal":
87             return 1.2 * L + 2 * D
88         else:
89             return 1.4 * L + 2 * D
90
91 # Effective length for cantilever Beam
92
93 def cl_8_3_3_Table_16_Effective_length_for_cantilever_beam(L, D,
94 Restraint_Condition_1, Restraint_Condition_2,
95 Loading_condition):
96     """
97         Calculate effective length for cantilever beam of projecting
length L as per cl.8.3.3
98
99     Args:
100         L - Projecting Length of cantiliver beam in mm (float)
101         D - Overall depth of he beam in mm (float)
102
103         Restrained_condition - Either "At support" or "At Top"
104
105         Restraint_Condition_1 - "At support"
106         Restraint_Condition_2 - "At Top"
107
108         At_support - Either "continuous, with lateral restraint to
top"
109             or "continuous, with partial torsional
restraint"
110             or "continuous, with lateral and torsional
restraint "
111             or "Restrained laterally,torsionally and
against rotation on plan "
112
113         At_top - Either "free"
114             or "lateral restraint to top flange"
115             or "Torsional restraint"
116             or "Lateral and torsional restraint"
117
118     Loading_condition - Either "Normal" or "Destabilizing"
119
120     Returns:
121         L_LT =
cl_8_3_3_Table_16_Effective_length_for_cantilever_beam
122     Note:
123         References:
124             IS800:2007, Table 16 (cl 8.3.3)
125
126     if Restraint_Condition_1 == "Continuous, with lateral restraint to
top flage":
127         if Restraint_Condition_2 == "Free":
128             if Loading_Condition == "Normal":
129                 return (3.0 * L + 0 * D)
130             else:
131                 return (7.5 * L + 0 * D)
132         if Restraint_Condition_2 == "Lateral restraint to top flage":
133             if Loading_Condition == "Normal":
134                 return (2.7 * L + 0 * D)

```

```

135
136         else:
137             return (7.5 * L + 0 * D)
138     if Restraint_Condition_2 == "Torsional restraint":
139         if Loading_condition == "Normal":
140             return (2.4 * L + 0 * D)
141         else:
142             return (4.5 * L + 0 * D)
143     if Restraint_Condition_2 == "Lateral and Torsional restraint":
144         if Loading_condition == "Normal":
145             return (2.1 * L + 0 * D)
146         else:
147             return (3.6 * L + 0 * D)
148     if Restraint_Condition_1 == "Continuous,with partial torsional
149     restraint":
150         if Restraint_Condition_2 == "Free":
151             if Loading_condition == "Normal":
152                 return (2.0 * L + 0 * D)
153             else:
154                 return (5.0 * L + 0 * D)
155     if Restraint_Condition_2 == "Lateral restraint to top flage":
156         if Loading_condition == "Normal":
157             return (1.8 * L + 0 * D)
158         else:
159             return (5.0 * L + 0 * D)
160     if Restraint_Condition_2 == "Torsional restraint":
161         if Loading_condition == "Normal":
162             return (1.6 * L + 0 * D)
163         else:
164             return (3.0 * L + 0 * D)
165     if Restraint_Condition_2 == " Lateral and Torsional
166     restraint":
167         if Loading_condition == "Normal":
168             return (1.4 * L + 0 * D)
169         else:
170             return (2.4 * L + 0 * D)
171     if Restraint_Condition_1 == "Continuous,with lateral and torsional
172     restraint":
173         if Restraint_Condition_2 == "Free":
174             if Loading_condition == "Normal":
175                 return (1.0 * L + 0 * D)
176             else:
177                 return (2.5 * l + 0 * D)
178     if Restraint_Condition_2 == "Lateral restraint to top flage":
179         if Loading_condition == "Normal":
180             return (0.9 * L + 0 * D)
181         else:
182             return (2.5 * L + 0 * D)
183     if Restraint_Condition_2 == "Torsional restraint":
184         if Loading_condition == "Normal":
185             return (0.8 * L + 0 * D)
186         else:
187             return (1.5 * L + 0 * D)
188     if Restraint_Condition_2 == " Lateral and Torsional restraint":
189         if Loading_condition == "Normal":
190             return (0.7 * L + 0 * D)
191         else:
192             return (1.2 * L + 0 * D)
193     if Restraint_Condition_1 == "Restrained laterally,torsionally and
194     against rotation on plan":
195         if Restraint_Condition_2 == "Free":
196             if Loading_condition == "Normal":

```

```

192         return (0.8 * L + 0 * D)
193     else:
194         return (1.4 * L + 0 * D)
195     if Restraint_Condition_2 == "Lateral restraint to top flage":
196         if Loading_condition == "Normal":
197             return (0.7 * L + 0 * D)
198         else:
199             return (1.4 * L + 0 * D)
200     if Restraint_Condition_2 == "Torsional restraint":
201         if Loading_condition == "Normal":
202             return (0.6 * L + 0 * D)
203         else:
204             return (0.6 * L + 0 * D)
205     if Restraint_Condition_2 == "Lateral and Torsional restraint":
206         if Loading_condition == "Normal":
207             return (0.5 * L + 0 * D)
208         else:
209             return (0.5 * L + 0 * D)

211 def cl_8_3_Effective_length_against_torsional_restraint(L, D, Beam_type,
212 , Restraint_Condition_1,
213
214     Restraint_Condition_2, Loading_Condition):
215     """
216         Calculation of effective length for given type of beam type as
217         per cl.8.3
218
219     Args:
220         L- Span of simply suppotred beams and girders in mm (float)
221     for
222         "
223         Simply_supported_with_no_lateral_restrained_to_the_compression_flanges",
224             Projecting Length of cantiliver beam in mm (float) for
225             "Cantilever_beam",
226             Length of relevent segment between the lateral restraint
227             in mm (float) for
228             "Simply_supported_with_intermediate_lateral_restraints",
229             Centre-to-centre distance of the restraint member in mm (
230             float) for
231             "
232             Beam_provided_with_members_to_give_effective_lateral_restrain_to_compression_flange_at_
233             "
234
235             D - Overall depth of he beam in mm (float)
236
237
238             Beam_type - Either "
239             Simply_supported_with_no_lateral_restrained_to_the_compression_flanges"
240                 or "
241             Simply_supported_with_intermediate_lateral_restraints"
242                 or "
243             Beam_provided_with_members_to_give_effective_lateral_restrain_to_compression_flange_at_
244             "
245                 or "Cantilever_beam"
246
247             FOR "
248             Simply_supported_with_no_lateral_restrained_to_the_compression_flanges"
249
250                 Restraint_Condition - Either "Torsional Restraint" or "wraping
251                 Restraint"

```

```

237
238     Restraint_Condition_1 - "Torsional Restraint"
239     Restraint_Condition_2 - "Warping_Restrain"
240
241         "Torsional Restrained" - Either "Fully_restrained" or
242             "
243             Partially_restrained_by_bottom_flange_support_condition" or
244                 "
245                 Partially_restrained_by_bottom_flange_support_condition"
246
247         "Warping_Restrain" - Either "Both_flange_fully_restrained" or
248             "compression_flange_fully_restrained"
249             or
250                 "
251                 Compression_flange_partially_restrained" or
252                     "Warping_not_restrained_in_both_flange"
253             "
254
255             FOR "Cantilever_beam"
256
257             Restrained_condition - Either "At support" or "At Top" for "
258             Cantilever_beam"
259
260                 Restraint_Condition_1 - "At support"
261                 Restraint_Condition_2 - "At Top"
262
263                 At_support - Either "continous, with lateral restraint to top"
264                     or "continous, with partial torsional
265                     restraint"
266                     or "continous, with lateral and torsional
267                     restraint"
268                     or "Restrained laterally,torsionally and
269                     against rotation on plan"
270
271
272             Returns :
273                 L_LT - Effective_length_of_beam_in_m (float)
274
275             Note:
276                 References:
277                     IS800:2007, cl 8.3.
278
279                 """
280
281             if Beam_type == "
282                 Simply_supported_with_no_lateral_restrained_to_the_compression_flanges"
283             :
284                 L_LT = cl_8_3_1_Effective_length_for_simply_supported_beams(L,
285                 D, Restraint_Condition_1,
286
287                 Restraint_Condition_2, Loading_Condition)
288             elif Beam_type == "

```

```

Simply_supported_with_intermediate_lateral_restraints":
285     L_LT = 1.2 * L
286     elif Beam_type == "Beam_provided_with_members_to_give_effective_lateral_restraint_to_compression_flange_at_"
287         L_LT = 1.2 * L
288     else:
289         L_LT = cl_8_3_3_Table_16_Effective_length_for_cantilever_beam(L,
290             D, Restraint_Condition_1,
291             Restraint_Condition_2, Loading_Condition)
292
293     return L_LT
294
295     # E-1 ELASTIC CRITICAL MOMENT
296
297     # E-1.1 General
298     # TODO:Calculate L_LT = L_LT =
299     cl_8_3_Effective_length_against_lateral_torsional_buckling(L,D,
300         Beam_type,Restraint_Condition_1,Restraint_Condition_2,Loading_Condition
301     )
302
303     def
304         Annex_E_1_1_elastic_critical_moment_corresponding_to_lateral_torsional_buckling_of_doub
305         (
306             I_y, I_w, I_t, G, E, L_LT):
307
308             """
309                 Calculate the elastic critical moment corresponding to lateral
310                     torsional buckling of a doubly symmetric prismatic beam
311                     subjected to uniform
312                         moment in the unsupported length and torsionally
313                     restraining lateral supports as per Annex E-1.1
314
315             Args:
316                 I_y - Moment of inertia about the minor axis (in quartic mm
317             ) (float)
318                 I_w - Warping constant of the cross- section (mm**4)(float)
319                 I_t - St. Venants torsion constant of the cross-section (mm
320             **4)(float)
321                 G - Modulus of rigidity (float)
322                 L_LT =
323             cl_8_3_Effective_length_against_lateral_torsional_buckling(L,D,
324                 Beam_type,Restraint_Condition_1,Restraint_Condition_2,Loading_Condition
325             )
326
327
328             Returns:
329                 M_cr - Elastic critical moment corresponding to lateral
330                     torsional
331                         buckling of doubly symmetric prismatic beam ( in N*
332                     mm) (float)
333
334             Note:
335                 Reference:
336                     IS800:2007, Annex - E-1.1
337
338             """
339
340             sum_value = (I_w / I_y) + (G * I_t * L_LT * L_LT) / (pi * pi * E *

```

```

I_y)

327     M_cr = ((pi * pi * E * I_y) / (L_LT * L_LT)) * ((sum_value) ** 0.5)
328
329     return M_cr
330
331
332 def Annex_E_Table_42_constant_c_1_c_2_c_3(Loading_and_Support_condition,
333     , si, K):
334     """
335         Calculate Value of constant c_1,c_2,c_3 as per Table_42 Annex-E
336         Args:
337             Loading_and_Support_condition - Either "Simply supported
338             with ends moments (M,si*M)"                                     or "simply Supported beam
339             with UDL"                                                       or "Fixed support with UDL"
340             with point load at centre"                                    or "Simply Supported beam
341             with point load at centre"                                    or "Fixed Supported beam
342             with point at L/4 distance from both ends"                  or "Simply Supported beam
343
344             Bending_Moment_diagram- BMD for "Simply supported with ends
345             moments (M,si*M)" by varying value of 'si' as-
346             si - [
347                 +1,+3/4,+1/2,+1/4,0,-1/4,-1/2,-3/4,-1 ]                         BMD for "simply Supported beam with
348                                         UDL"                                         si - 0 (Assumed value)
349                                         BMD for "Fixed support with UDL"
350                                         si - 0 (Assumed value)
351                                         BMD for "Simply Supported beam with
352                                         point load at centre"                           si - 0 (Assumed value)
353                                         BMD for "Fixed Supported beam with
354                                         point load at centre"                           si - 0 (Assumed value)
355                                         BMD for "Simply Supported beam with
356                                         point at L/4 distance from both ends"           si - 0 (Assumed value)
357
358             Returns:
359                 Value of constant c_1,c_2,c_3
360
361             Note:
362                 References:
363                     IS800:2007, Table 42, cl E-1.2
364
365
366             if Loading_and_Support_condition == "Simply supported with ends
367             moments (M,si*M)":
368                 if si == 1:
369                     if K == 1.0:
370                         return {"c1": 1.000, "c2": 0, "c3": 1.000}
371                     if K == 0.7:
372                         return {"c1": 1.000, "c2": 0, "c3": 1.113}
373                     if K == 0.5:
374                         return {"c1": 1.000, "c2": 0, "c3": 1.144}

```

```

374     if si == +3 / 4:
375         if K == 1.0:
376             return {"c1": 1.141, "c2": 0, "c3": 0.998}
377         if K == 0.7:
378             return {"c1": 1.270, "c2": 0, "c3": 1.565}
379         if K == 0.5:
380             return {"c1": 1.305, "c2": 0, "c3": 2.283}
381     if si == +1 / 2:
382         if K == 1.0:
383             return {"c1": 1.323, "c2": 0, "c3": 0.992}
384         if K == 0.7:
385             return {"c1": 1.473, "c2": 0, "c3": 1.556}
386         if K == 0.5:
387             return {"c1": 1.514, "c2": 0, "c3": 2.271}
388     if si == +1 / 4:
389         if K == 1.0:
390             return {"c1": 1.879, "c2": 0, "c3": 0.939}
391         if K == 0.7:
392             return {"c1": 2.092, "c2": 0, "c3": 1.473}
393         if K == 0.5:
394             return {"c1": 2.150, "c2": 0, "c3": 2.150}
395     if si == 0:
396         if K == 1.0:
397             return {"c1": 1.563, "c2": 0, "c3": 0.977}
398         if K == 0.7:
399             return {"c1": 1.739, "c2": 0, "c3": 1.531}
400         if K == 0.5:
401             return {"c1": 1.788, "c2": 0, "c3": 2.235}
402     if si == -1 / 4:
403         if K == 1.0:
404             return {"c1": 2.281, "c2": 0, "c3": 0.855}
405         if K == 0.7:
406             return {"c1": 2.538, "c2": 0, "c3": 1.340}
407         if K == 0.5:
408             return {"c1": 2.609, "c2": 0, "c3": 1.957}
409     if si == -1 / 2:
410         if K == 1.0:
411             return {"c1": 2.704, "c2": 0, "c3": 0.676}
412         if K == 0.7:
413             return {"c1": 3.009, "c2": 0, "c3": 1.059}
414         if K == 0.5:
415             return {"c1": 3.093, "c2": 0, "c3": 1.546}
416     if si == -3 / 4:
417         if K == 1.0:
418             return {"c1": 2.927, "c2": 0, "c3": 0.366}
419         if K == 0.7:
420             return {"c1": 3.009, "c2": 0, "c3": 0.575}
421         if K == 0.5:
422             return {"c1": 3.093, "c2": 0, "c3": 0.837}
423     if si == -1:
424         if k == 1.0:
425             return {"c1": 2.752, "c2": 0, "c3": 0}
426         if k == 0.7:
427             return {"c1": 3.063, "c2": 0, "c3": 0}
428         if k == 0.5:
429             return {"c1": 3.149, "c2": 0, "c3": 0}
430     if Loading_and_Support_condition == "simply Supported beam with UDL"
431     :
432         if si == 0:
433             if K == 1.0:
434                 return {"c1": 1.132, "c2": 0.459, "c3": 0.525}

```

```

434         if K == 0.5:
435             return {"c1": 0.972, "c2": 0.304, "c3": 0.980}
436     if Loading_and_Support_condition == "Fixed support with UDL":
437         if si == 0:
438             if K == 1.0:
439                 return {"c1": 1.285, "c2": 1.562, "c3": 0.753}
440             if K == 0.5:
441                 return {"c1": 0.712, "c2": 0.652, "c3": 1.070}
442     if Loading_and_Support_condition == "Simply Supported beam with
443         point load at centre":
444         if si == 0:
445             if K == 1.0:
446                 return {"c1": 1.365, "c2": 0.553, "c3": 1.780}
447             if K == 0.5:
448                 return {"c1": 1.070, "c2": 0.432, "c3": 3.050}
449     if Loading_and_Support_condition == "Fixed Supported beam with
450         point load at centre":
451         if si == 0:
452             if K == 1.0:
453                 return {"c1": 1.565, "c2": 1.257, "c3": 2.640}
454             if K == 0.5:
455                 return {"c1": 0.938, "c2": 0.715, "c3": 4.800}
456     if Loading_and_Support_condition == "Simply Supported beam with
457         point at L/4 distance from both ends":
458         if si == 0:
459             if K == 1.0:
460                 return {"c1": 1.046, "c2": 0.430, "c3": 1.120}
461             if K == 0.5:
462                 return {"c1": 1.010, "c2": 0.410, "c3": 1.390}
463
464 # E-1.2 Elastic Critical Moment of a Section Symmetrical About Minor
465 # Axis
466 # TODO: Calculate c_1,c_2,c_3 = Annex_E_Table_42_constant_c_1_c_2_c_3(
467 # Loading_and_Support_condition,si,K)
468 def Elastic_critical_moment_of_a_section_symmetrical_about_minor_axis(
469 L_LT, c_1, c_2, c_3, E, K, K_w, y_g, A_e, b,
470 t
471 , I_fc, I_ft, I_y, G, h, h_L, h_y, n,
472 I_section=True, Open_section=True,
473 Plain_flange=False):
474 """
475     Calculate the elastic critical moment for lateral torsional
476     buckling for beam which is
477         symmetrical only about the minor axis, and bending about major
478         axis as per Annex E-1.2
479
480     Args:
481         c_1,c_2,c_3- Annex_E_Table_42_constant_c_1_c_2_c_3(
482 Loading_and_Support_condition,si,K)
483             K - Effective length factors of the unsupported length
484             accounting for boundry condition
485                 at the end letral supports. It is analogus to the
486                 effective length factirs for
487                     compression members with end rotational restraint.
488             K_w -Warping restraint factor.
489             y_g -y distance between the point of application of the
490                 load and the shear centre of
491                     the cross-section and is positive when the load is
492                     acting towards the shear

```

```

479             centre from the point of application.
480             y_s- co-ordinate of the shear centre with respect to
centriod,positive when the shear
481                 centre is on the compression side of the centriod.
482             y,z- co-ordinate of the elemental area with respect to
centriod of the section
483             E - Youngs modulus of elasticity ( N per sq.mm)(float)
484             G- Modulus of regidity (float)
485             I_y - Moment of inertia about minor axis (in mm**4)(float)
486             I_fc - Moment of inertia of the compression flange about
minor axis of the entire section (in mm**4)(float)
487             I_ft - Moment of inertia of the tension flange about minor
axis of the entire section (in mm**4)(float)
488             I_w - The wraping constant either for "
I_section_mono_symmetric_about_weak_axis" or for
489                                         "Angle,Tee,
narrow_rectangle_section and approximetly for hollow_section"
490             I_t - Torsion constant either "for open_section" or "
hollow_section"
491             A_e - Area encloeo by the section (in sq mm)(float)
492             b - Breadth of the elements of the section(mm)(float)
493             t - Thickness of the elements of the section (mm)(float)
494             h_L- Height of the lip in mm(float)
495             h- overall height of the section in mm(float)
496             h_y - Distance between shear centre of the two flange of
the cross-section in mm (float)
497             Flange type - Either "Plain_flange" or "Lipped_flange"
498             L_LT =
cl_8_3_Effective_length_against_lateral_torsional_buckling(L,D,
Beam_type,Restraint_Condition_1,Restraint_Condition_2,Loading_Condition
)
500
501             Returns:
502             M_cr-
Elastic_critical_moment_of_a_section_symmetrical_about_minor_axis (in N
*mm)(float)
503
504             Note:
505             References:
506             IS800:2007 ,cl E-1.2
507             """
508
509             beta_f = I_fc / (I_ft + I_fc)
510
511             if I_section is True:
512                 I_w = (1 - beta_f) * beta_f * I_y * h_y * h_y
513             else:
514                 I_w = 0
515
516             if Plain_flange is True:
517                 if beta_f > 0.5:
518                     y_j = 0.8 * (2 * beta_f - 1) * h_y / 2.0
519                 else:
520                     y_j = 1.0 * (2 * beta_f - 1) * h_y / 2.0
521             else:
522                 if beta_f > 0.5:
523                     y_j = 0.8 * (2 * beta_f - 1) * (1 + h_L / h_) * h_y / 2.0
524                 else:
525                     y_j = (2 * beta_f - 1) * (1 + h_L / h) * h_y / 2
526
527             if Open_section is True:
528                 sum_value = 0

```

```

527     for i in range(n - 1):
528         sum_value += (b * t * t * t) / 3
529         I_t = sum_value
530     else:
531         sum_value = 0
532         for i in range(n - 1):
533             sum_value += (b / t)
534
535         I_t = 4 * A_e / sum_value
536
537         T_1 = c_1 * (pi * pi * E * I_y) / (L_LT)
538         T_2 = (K / K_w) ** 2 * (I_w / I_y)
539         T_3 = (G * I_t * L_LT * L_LT) / (pi * pi * E * I_y)
540         T_4 = ((c_2 * y_g) - (c_3 * y_j)) ** 2
541         T_5 = ((c_2 * y_g) - (c_3 * y_j))
542
543         M_cr = T_1 * (((T_2 + T_3 + T_4) ** 0.5) - T_5)
544
545     return M_cr
546 # =====

```

## Appendix E

# Creating class for sectional properties of I section

```
1 import math
2
3 class I_sectional_Properties(object):
4     def __init__(self,D,B,t_w,t_f,alpha=90,r_1=0,r_2=0):
5         """ Calculation of sectional properties of built-up I section
6         Args:
7             D- depth of beam in mm
8             B- Width of flange in mm
9             t_w- thickness of web in mm
10            t_f- thickness of flange in mm
11            alpha- flange slope in degree
12            r_1-root radius in mm
13            r_2-toe radius in mm
14        Return:
15            A- Sectional Area of the section in mm**2
16            M - Mass (kg/m)
17            I_zz - second moment of area in cm**4
18            I_yy - second moment of area in cm**4
19            r_z - radius of gyration in cm
20            r_y - radius of gyration in cm
21            Z_ez - elastic modulus in cm**
22            Z_ey - elastic modulus in cm**3
23            Z_pz - plastic modulus in cm**3
24            Z_py - plastic modulus in cm**3
25
26        """
27
28        self.A = ((2*B*t_f) + ((D-2*t_f)*t_w))/100
29        self.M = 7850 * self.A / 10000
30        self.I_zz = ((D - 2*t_f)**3 * t_w / 12 + (B*t_f**3)/6+(B/2*t_f*(D-
31        t_f)**2))/10000
32        self.I_yy = ((D-2*t_f)*t_w**3 /12 + B**3*t_f/6)/10000
33        self.r_z = math.sqrt(self.I_zz / self.A)
34        self.r_y = math.sqrt(self.I_yy / self.A)
35        self.Z_ez = (self.I_zz * 2*10) / (D)
36        self.Z_ey = (self.I_yy * 2*10) / (B)
37        self.y_p = (((D - 2*t_f)**2*t_w/8 + B*t_f*(D-t_f)/2) / ((D-t_f)/2*t_
38        w + B*t_f ))/10
39        self.Z_pz = (2 * (self.A / 2 * self.y_p))
40        self.z_p = (((((D-2*t_f)*t_w**2)/8 + (B*t_f*B)/4)/((D-2*t_f)*t_w/2 +
41        (B*t_f))))
```

39

```
    self.Z_py = 2 * (self.A / 2 * self.z_p)
```

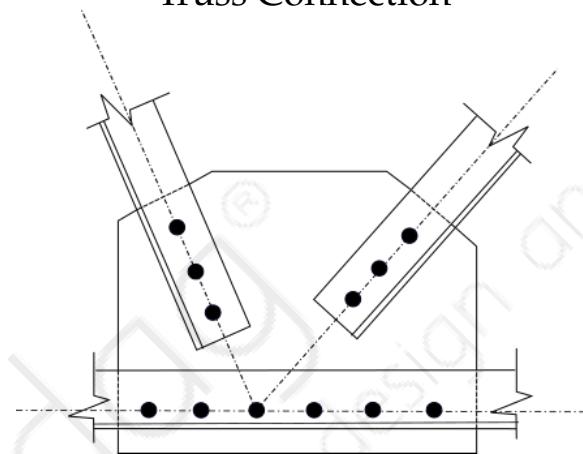
## **Appendix F**

### **DDCL for Bolted Truss Connection**



Design and Detailing Checklist (DDCL)  
and  
Design and Detailing Query (DDQ)

### Truss Connection



Prepared by:  
**Rachna Gupta**

Under the guidance of:  
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Indian Institute of Technology, Bombay

July 10, 2019

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# User Inputs

- Connecting members
  - Truss Member Sections\*
- Types of Connectivity\*
  - Bolted
- Factored loads
  - Axial Force (kN)
- Material Property of section
  - $f_u$  (MPa)\*
  - $f_y$  (MPa)\*
- Fasteners Details
  - Bolt Diameter (mm)\*
  - Bolt Type \*
  - Property class \*
- Detailing
  - Angle of inclination (degree)\*
- Plate
  - Thickness (mm)\*
  - $f_u$  (MPa)\*
  - $f_y$  (MPa)\*

# **Design and Detailing Checks**



# Check 1

## Bolt Design

The truss members and gusset plate are connected by bolts.

### 1.1 Gusset Plate

#### 1.1.1 Gusset plate thickness ( $t_g$ )

Thickness of the gusset plate provided is usually equal to or slightly higher than members that are connected to gusset plate.

Thickness of gusset plate is calculated on the basis of maximum force acting on the truss members and is given by the table. [Reference:Table 5.12 Design of steel structure by N.Subramanian]

Maximum design force in diagonal(KN)	upto 200	200-450	450-750	750-1650	1650-2250	2250-3000
Thickness of gusset plate(mm)	8	10	12	16	18	20

### 1.2 Bolt Value

#### 1.3 Bearing type bolts

##### 1.3.1 Design strength of bolt ( $V_{db}$ )

[Reference: Cl. 10.3.2, IS 800:2007]

The design strength of bolt is taken as the smaller of the value as governed by shear,  $V_{dsb}$  (1.3.2) and bearing  $V_{dpb}$  (1.3.3).

$$V_{db} = \min (V_{dsb}, V_{dpb}) \quad (1.1)$$

##### 1.3.2 Shear capacity ( $V_{dsb}$ )

[Reference: Cl. 10.3.3, IS 800:2007]

Currently, conservatively assuming all the shear planes passes through the threads of the bolt. Shear capacity of bearing bolts,

$$V_{dsb} = \frac{f_u n_n A_{nb}}{\sqrt{3} \gamma_{mb}} \quad (1.2)$$

Where,

$V_{dsb}$  = design strength of bolt, as governed by shear strength;

$f_u$  = ultimate tensile strength of a bolt;

$n_n$  = number of shear planes with threads intercepting the shear plane;

$A_{nb}$  = net shear area of the bolt at threads, taken as the area corresponding to root diameter at the thread;

$\gamma_{mb}$  = partial safety factor for bolt

### 1.3.3 Bearing capacity ( $V_{dpb}$ )

[Reference: Cl. 10.3.4, IS 800:2007]

$$V_{dpb} = \frac{2.5 k_b d t f_u}{\gamma_{mb}} \quad (1.3)$$

Where,

$k_b$  is smaller of  $\frac{e}{3d_0}$ ,  $\frac{p}{3d_0} - 0.25$ ,  $\frac{f_{ub}}{f_u}$ , 1.0;

$e, p$  = end and pitch distances of the bolt along line of action respectively;

$d, d_0$  = diameter of bolt and bolt hole respectively;

$t$  = summation of the thicknesses of the connected plates experiencing bearing stress in the same direction;

$\gamma_{mb}$  = partial safety factor.

## 1.4 Friction grip type bolts

### 1.4.1 Slip resistance ( $V_{dsf}$ )

[Reference: Cl. 10.4.3, IS 800:2007]

$$V_{dsf} = \frac{F_o \mu_f n_e K_h}{\gamma_{mf}} \quad (1.4)$$

$\mu_f$  = coefficient of friction (slip factor);

$n_e$  = number of effective interfaces offering frictional resistance to slip;

$K_h$  = 1.0 for bolts in clearance holes and 0.85 for bolts in oversized holes;

$F_o$  = proof load =  $A_{nb} f_0$ ;

$f_0$  = proof stress  $0.7 A_{ub}$ ;

$\gamma_{mf}$  = partial safety factor.

## 1.5 Bolt Capacity

From here on,  $V_{bolt}$  is used where bolt capacity is considered.  $V_{bolt}$  is taken as  $V_{dsf}$  if friction grip bolt is considered and  $V_{db}$ , if bearing bolt is considered.

## 1.6 Check of long joint

[Reference: Cl. 10.3.3.1 IS 800 : 2007]

when  $l_j \geq 15d$ , design capacity will be reduced by factor  $\beta_{lj}$ .

$$\beta_{lj} = 1.075 - 0.005(l_j/d), 0.75 \leq \beta_{lj} \leq 1.0 \quad (1.5)$$

where,

$l_j$  = length of joint (measured in the direction of load transfer);

$d$  = nominal diameter of the bolt.

## 1.7 Check of large grip length

[Reference: Cl. 10.3.3.2 and Cl. 10.3.3.1 IS 800 : 2007]

when  $l_g \geq 5d$ , the design shear capacity is reduced by a factor  $\beta_{lg}$ .

$$\beta_{lg} = \frac{8}{3 + l_g/d} \quad (1.6)$$

where,

$l_g$  = total thickness of the connected plates (grip length);

$d$  = nominal diameter of the bolt.

Note:  $\beta_{lg}$  should not be greater than  $\beta_{lj}$

## 1.8 Bolt capacity

$$V'_{db} = V_{bolt} \beta_{lj} \beta_{lg} \quad (1.7)$$

## Check 2

# Number of Bolts

### 2.1 Minimum number of bolts ( $n$ )

Number of bolts required for each truss member( $n$ ) is given by the equation;

$$n = \frac{P}{V_{bolt}} \quad (2.1)$$

If leg size of truss member section is than 130mm, then linear bolt raw will be provided. If leg size is greater than 130mm than either linear bolt raw or staggered bolt raw can be provided (chain bolting is usually not preferred as staggered bolting is more efficient).

### 2.2 Number of bolts in zero force member ( $n_0$ )

[Reference:Cl 10.7 IS 800: 2007 ]

When no axial force is acting on the truss member then a force of at least 0.3times the member design capacity acts at the ends of tensile or compression member and minimum number of bolt is calculated on this basis.

$$F_d = \frac{f_y A}{\gamma_{m0}} \quad (2.2)$$

where,

$F_d$  = Member design capacity;

$$n_0 = \frac{0.3 F_d}{V_{bolt}} \quad (2.3)$$

## Check 3

# Gusset Plate Checks

### 3.1 Whitmore effective width ( $B_{eff}$ )

[Reference: Page No. 365 Design of steel by structure N.Subramanian 13th Edition]

Maximum direct stress(compression or tension) in gusset plate from an individual member is estimated adequately by ensuring that the member force is distributed uniformly over an effective area given by  $30^\circ$  dispersion from outer row of fasteners as shown in figures:

#### 3.1.1 For one bolt line

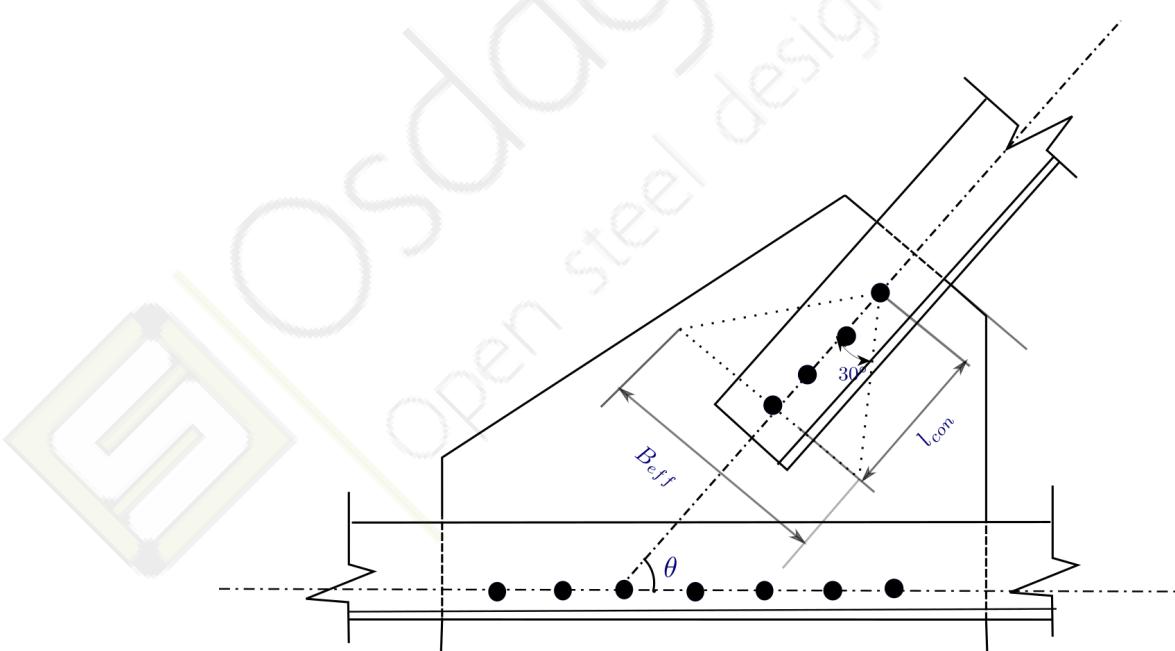


Figure 3.1: Whitmore Effective Width for Linear bolting arrangement

$$B_{eff} = 2l_{con}\tan(30^\circ) \quad (3.1)$$

### 3.1.2 For staggered bolts

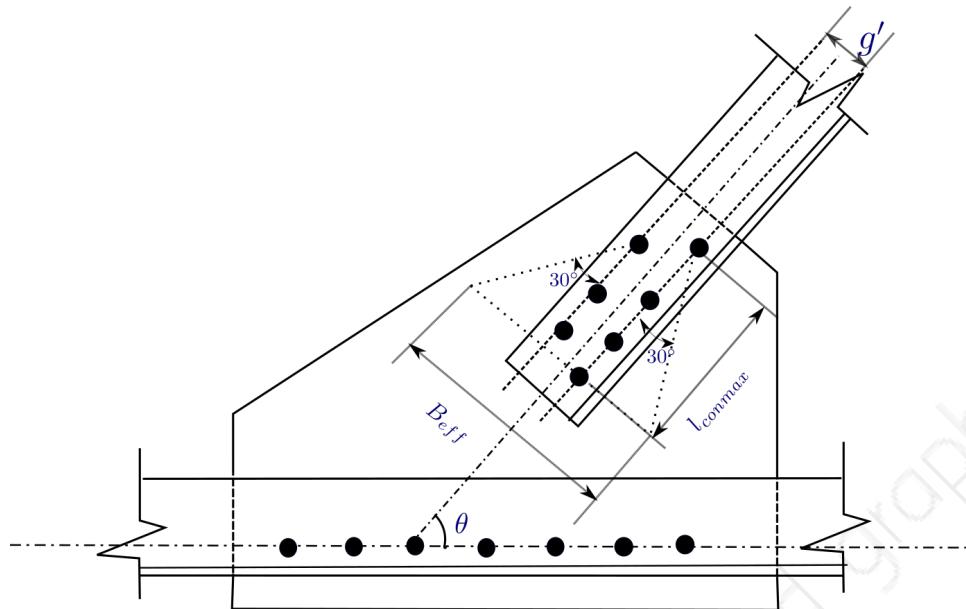


Figure 3.2: Whitmore Effective Width for Staggered bolting arrangement

$$B_{eff} = g' + (2l_{conmax}\tan(30^\circ)) \quad (3.2)$$

where,

$g'$  = gauge length between the staggered bolts;

$l_{conmax}$  = maximum connection length of staggered bolts for each member.

## 3.2 Check for Tension

### 3.2.1 Check for Tension Yielding

[Reference: Cl 6.2 IS 800: 2007 ]

$$\frac{P}{(B_{eff}t_g)} \leq \frac{f_y}{\gamma_{m0}} \quad (3.3)$$

where,

$P$  = Factored Axial force on each member;

$B_{eff}$  = Whitmore effective width;

$t_g$  = Gusset plate thickness;

$f_y$  = yield strength of plate;

$\gamma_{m0}$  = Partial factor of safety for yielding.

### 3.2.2 Check for Tension Rapture

[Reference: Cl 6.3 IS 800: 2007 ]

$$\frac{P}{(B_{eff} - nd_0)t_g} \leq \frac{0.9f_u}{\gamma_{m1}} \quad (3.4)$$

where,

$P$  = Axial force on each member;

$d_0$  = bolt hole diameter;

$n$  = numbers of bolts

$B_{eff}$  = Whitmore effective width;

$t_g$  = Gusset plate thickness;

$f_u$  = ultimate strength of plate;

$\gamma_{m0}$  = Partial factor of safety.

### 3.3 Whitmore equivalent column length ( $l_c$ )

[Reference: Page No. 365 Design of steel by structure N.Subramanian 13th Edition]

Whitmore equivalent column length is defined as average of the three lengths projected from the whitmore section,section, in the direction of member, to the fastener lines of the adjoining members. The three lengths are taken at the two ends of the width and at the center. If Whitmore section intersects an adjoining member bolt line, the length at that end is assumed to be zero. Conservatively, Whitmore equivalent column length can also be taken as the distance from center of member to the fasteners lines of adjoining members.

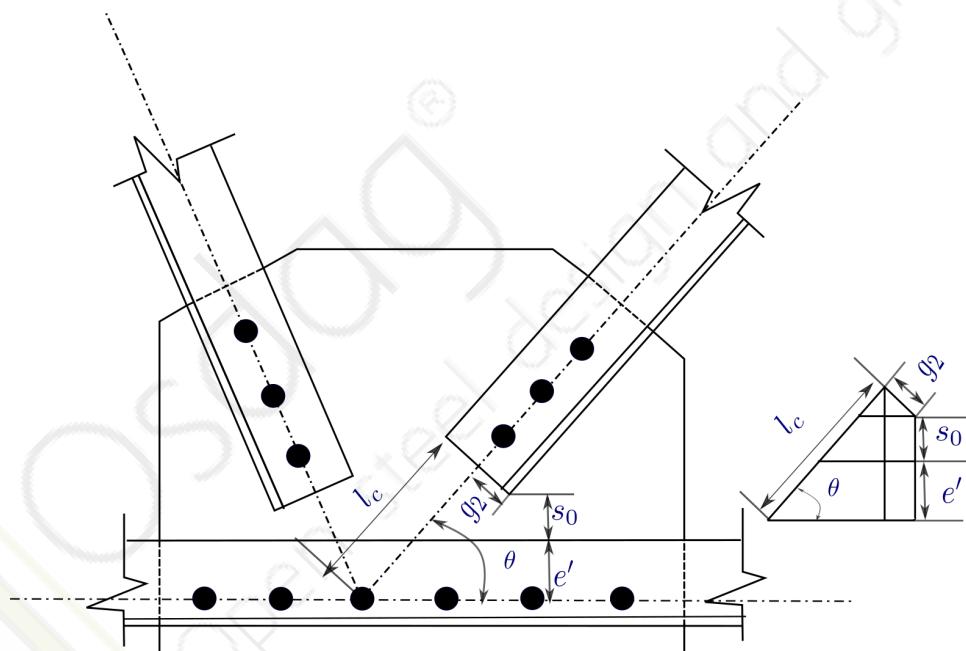


Figure 3.3: Equivalent Column Length

$$l_c = \frac{s_0 + g_1 + g_2 \cos(\theta)}{\sin(\theta)} \quad (3.5)$$

where,

$s_0$  = spacing between bottom chord and the connected truss member;

$e'$  = edge distance of bottom chord;

$g_2$  = gauge length of connected truss member;

$\theta$  = angle of inclination of connected truss member with bottom bottom chord.

### 3.4 Check for Buckling Failure

[Reference:Cl 7.1.2.1 IS 800: 2007 ]

$$f_{cd} = \frac{f_y/\gamma_m}{\phi + \sqrt{\phi^2 - \lambda^2}} \quad (3.6)$$

where,

$$\phi = 0.5[1 + \alpha(\lambda - 0.2) + \lambda^2]$$

$\lambda$  = non-dimensional effective slenderness ratio;

$$= \sqrt{f_y/f_{cc}}$$

$$f_{cc} = \text{Euler Buckling stress} = \frac{\pi^2 E}{(Kl_c/r_{min})^2}$$

$K = 0.7$ , Effective length factor;

$l_c$  = Whitmore equivalent column length;

$$r_{min} = \text{radius of gyration of plate} = t_g/\sqrt{12};$$

$f_{cd}$  = Design Compressive stress;

$t_g$  = Thickness of gusset plate.

$$\frac{F}{B_{eff}t_g} \leq f_{cd} \quad (3.7)$$

where,

$F$  = Factored Axial force on truss member;

$B_{eff}$  = Whitmore effective width.

## Check 4

# Check for Truss Member

### 4.1 Block failure check

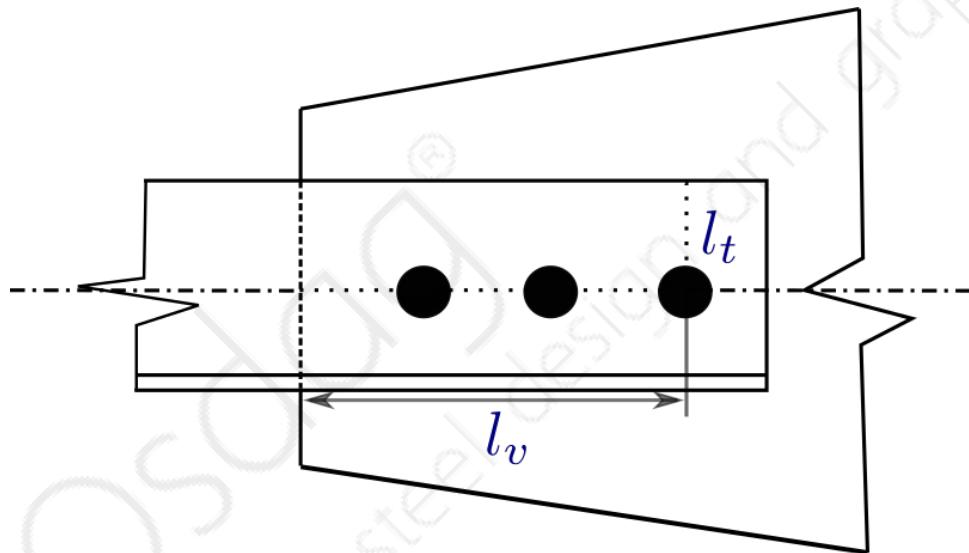


Figure 4.1: Block Failure of Truss member

$$T_{db1} = \frac{A_{vg}f_y}{\sqrt{3}\gamma_{m0}} + \frac{0.9A_{tn}f_u}{\gamma_{m1}} \quad (4.1)$$

$$T_{db2} = \frac{0.9A_{vn}f_u}{\sqrt{3}\gamma_{m1}} + \frac{A_{tg}f_y}{\gamma_{m0}} \quad (4.2)$$

where,

$A_{vg}$  = Minimum gross area in shear along bolt line parallel to external force =  $l_v * t$

$A_{vn}$  = Minimum net area in shear along bolt line parallel to external force =  $A_{vg} - (n_r - 0.5)d_0$

$A_{tg}$  = Minimum gross area in tension from the bolt hole to the toe of the angle, end bolt line, perpendicular to the line of force =  $l_t * t$

$A_{tn}$  = Minimum net area in tension from the bolt hole to the toe of the angle, end bolt line, perpendicular to the line of force =  $A_{tg} - (n_c - 0.5)d_0$

$n_r$  = number of bolt rows

$n_c$  = number of bolt columns

$f_u$  = Ultimate stress of the plate material

$f_y$  = Yield stress of the plate material

$\gamma_{m0} = 1.10$

$\gamma_{m1} = 1.25$

## Check 5

# Detailing

The size and shape of the gusset plates are decided based on the direction of various members meeting at a joint. The plate outlines are fixed so as to meet the minimum edge distance specified for the bolts that are used to connect various members at a particular joint and also it should give aesthetic appearance.

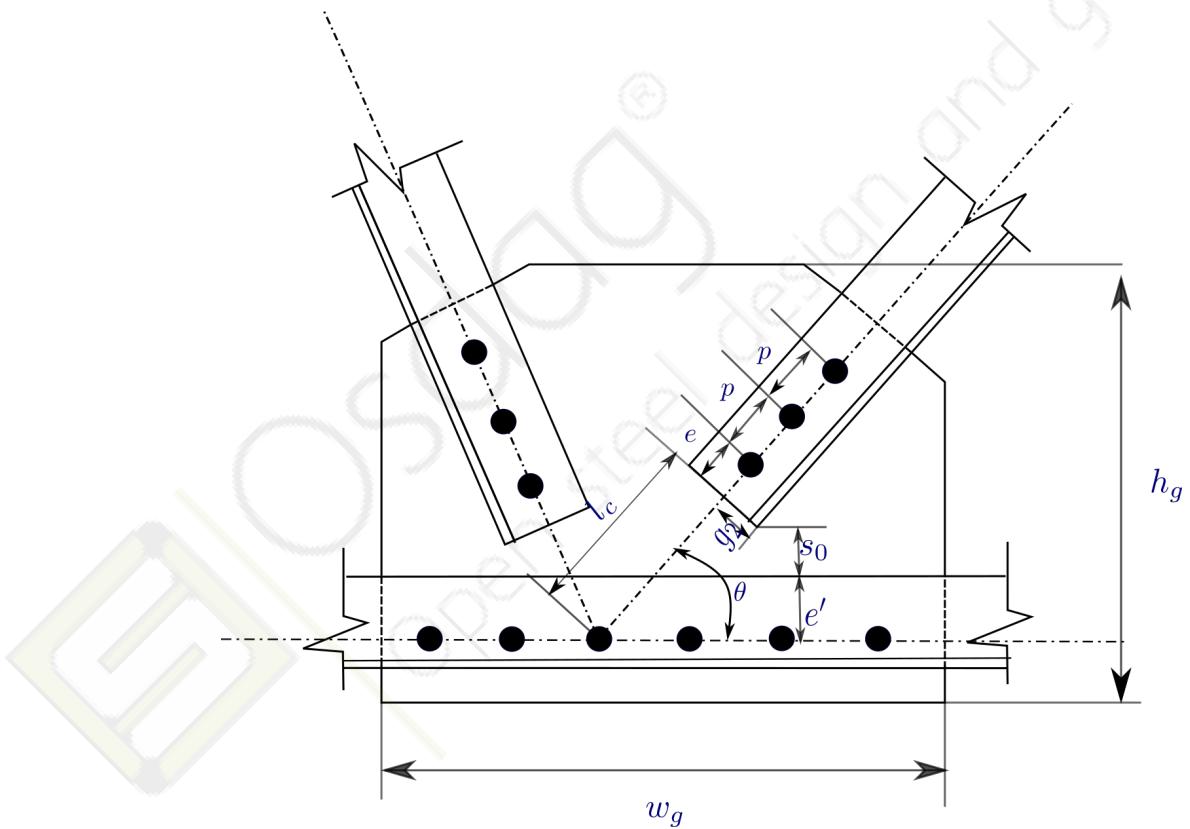


Figure 5.1: Gusset Plate detailing

### 5.1 Pitch (p) and Gauge (g)

[Reference: Cl. 10.2.2 and 10.2.3, IS 800 : 2007]

$$2.5 d \leq p \text{ or } g \leq \min(32 t, 300 \text{ mm}) \quad (5.1)$$

Where,  
 $d$  = diameter of bolt;  
 $t$  = thickness of the thinner plate.

## 5.2 End (e) and Edge (e')

[Reference: Clause 10.2.4, IS 800 : 2007]

$$[1.5 \text{ or } 1.7] \times d_0 \leq e/e' \leq 12 t \varepsilon \quad (5.2)$$

$$\varepsilon = \sqrt{\frac{250}{f_y}} \quad (5.3)$$

Where,  
1.5 for machine cut and 1.7 for hand cut;  
 $d_0$  = diameter of the hole;  
 $t$  = thickness of the thinner plate;  
 $f_y$  = yield stress of the plate.

## 5.3 Gusset plate Dimensions

### 5.3.1 Height of Gusset plate ( $h_g$ )

$$h_g = \max[(l_c + l_{con} + 2e)\sin(\theta)] \quad (5.4)$$

### 5.3.2 Width of gusset plate ( $w_g$ )

#### 5.3.2.1 case 1

When truss connection has no member in  $\theta_{max} < 90^\circ$  or  $\theta_{min} > 90^\circ$ , width of gusset plate is given by;

$$L_1 = \max[(l_{con} + l_c + 2e)\cos(\theta)] \quad (5.5)$$

$$L_2 = p(n - 1) + e \quad (5.6)$$

$$w_g = L_1 + L_2 \quad (5.7)$$

#### 5.3.2.2 case 2

When truss connection has members in  $\theta < 90^\circ$  and  $\theta > 90^\circ$ , width of gusset plate is given by;

#### 5.3.2.3 For ( $\theta < 90^\circ$ )

$$L_1 = \max[(l_{con_i} + l_{c_i} + 2e)\cos(\theta)] \quad (5.8)$$

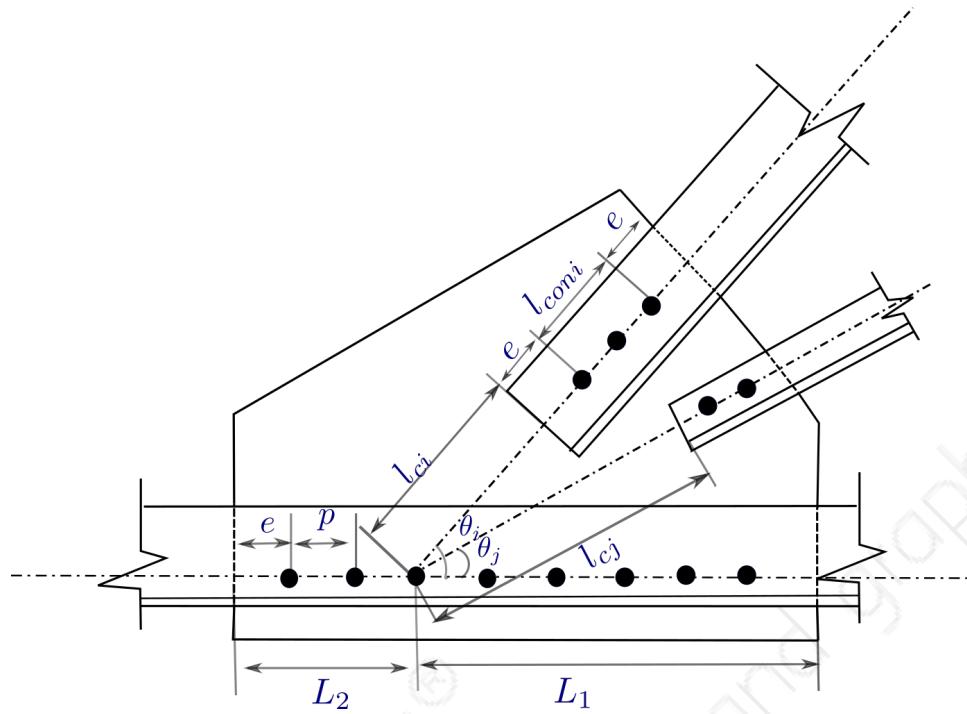


Figure 5.2: Width of Gusset Plate

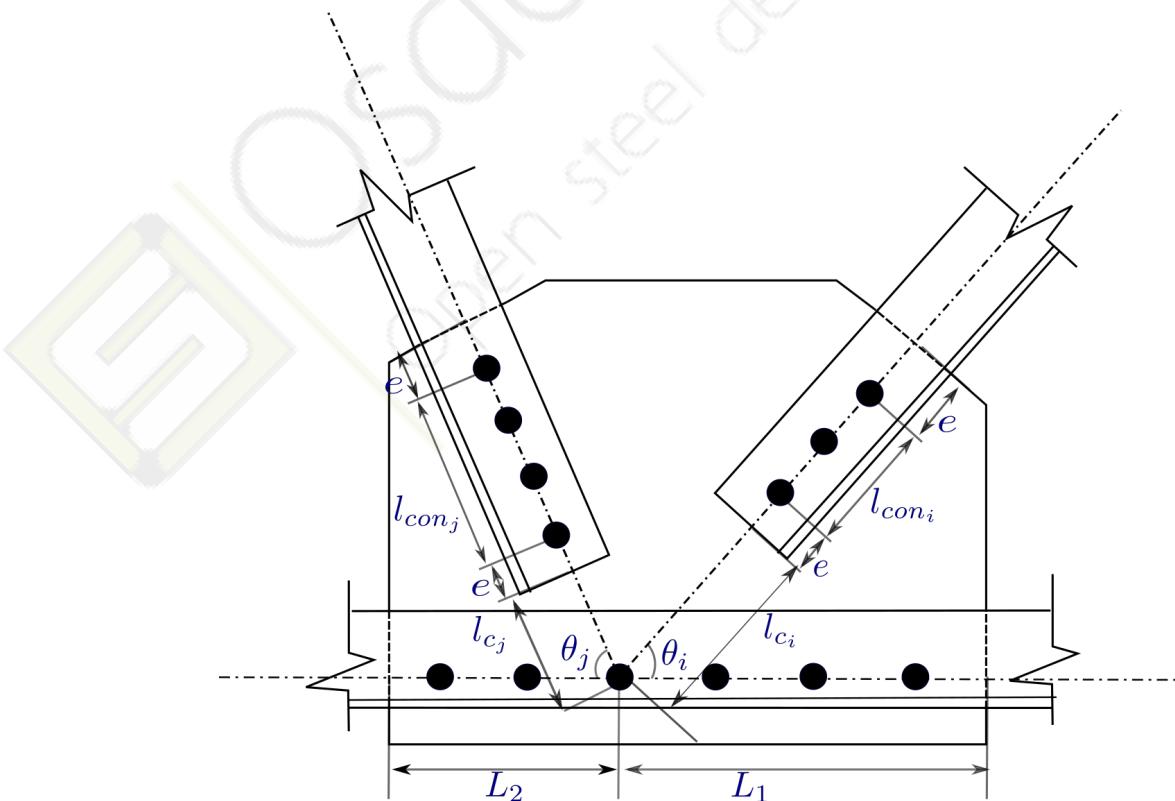


Figure 5.3: Width of Gusset Plate

#### 5.3.2.4 For ( $\theta > 90^\circ$ )

$$L_2 = \max(l_{con_j} + l_{c_j} + 2e) \cos(\theta) \quad (5.9)$$

$$w_g = L_1 + L_2 \quad (5.10)$$

where,

$n$  = number of bolts in bottom chord.

$l_{con}$  = connection length of truss members;

$l_c$  = Whitmore equivalent column length;

$e$  = end distance for truss member;

$p$  = pitch for the truss member;

$n$  = number of bolts;

$\theta_{max}$  = angle of inclination of diagonal or vertical truss member with C.G of bottom chord.

## **Appendix G**

### **DDCL for Welded Truss Connection**



Design and Detailing Checklist (DDCL)  
and  
Design and Detailing Query (DDQ)

## Welded Truss Connection

Prepared by:  
**Rachna Gupta**

Under the guidance of:  
**Prof. Siddhartha Ghosh**



Indian Institute of Technology, Bombay

July 13, 2019

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# **Reviewer Details & Guideline(s) for filling DDCL/DDQ**

1. Name of the reviewer:

2. Institute/Company/Organization:

3. Designation:

- This document is for Design and Detailing Check List (DDCL) and Design and Detailing Query (DDQ) created by Osdag team, IIT Bombay.
- The checks are documented algorithmically and chapter wise in the document where the checks and sub-checks are given in the section and subsection respectively.
- Reference of the check is given just below the check title
- Each check has an associated checkbox and a comment box for giving feedback. The checkbox can be checked.
- If you check on the 'Not Ok' checkbox during the review, please specify your reason in the comment box with reference(s) (if any). It is mandatory!
- Send the document after review to [sghosh@civil.iitb.ac.in](mailto:sghosh@civil.iitb.ac.in).

**For any queries or help on filling the feedback document, contact Rachna Gupta at [[rachna291998@gmail.com](mailto:rachna291998@gmail.com)]**

# Reviewer Details



# User Inputs

- Connecting members  
Truss Member Sections\*
- Connectivity\*  
Welded
- Material Property
  - $f_u$  (MPa)\*
  - $f_y$  (MPa)\*
- Factored loads
  - Axial Force (kN)
- Detailing
  - Angle of inclination(degree)\*
- Plate
  - Thickness (mm)\*
  - $f_u$  (MPa)\*
  - $f_y$  (MPa)\*
- Weld size
  - weld size (mm)\*

# **Design and Detailing Checks**



# Check 1

## Weld Design

Truss members and gusset plates are connected by weld

### 1.1 Gusset plate thickness ( $t_g$ )

Thickness of the gusset plate provided is usually equal to or slightly higher than members that are connected to gusset plate.

Thickness of gusset plate is calculated on the basis of maximum force acting on the truss members and is given by the table. [Reference:Table 5.12 Design of steel structure by N.Subramanian]

Maximum design force in diagonal(KN)	upto 200	200-450	450-750	750-1650	1650-2250	2250-3000
Thickness of gusset plate(mm)	8	10	12	16	18	20

### 1.2 Weld Length of Truss Members( $l_w$ )

[Reference: Page no. 484 Design of steel structure by N.Subramanian Edition 13th]

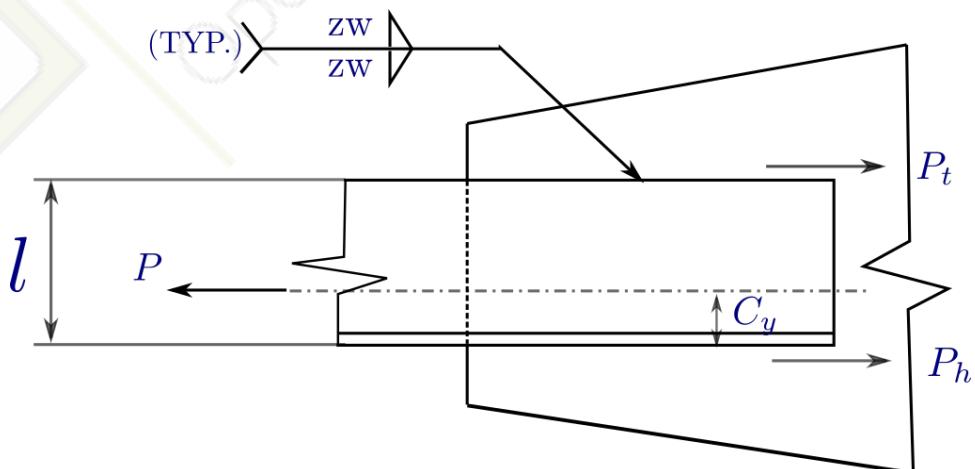


Figure 1.1: Balancing the weld on a tension member connection

$$f_w = \frac{t_t f_u}{\sqrt{3} \gamma_{m1}} \quad (1.1)$$

$$P_t = \frac{F C_y}{l} \quad (1.2)$$

$$P_h = F - P_t \quad (1.3)$$

where,

$f_w$  = Strength of weld;

$F$  = Axial Force on truss member;

$P_h$  = Axial force resisted by weld in hill side;

$P_t$  = Axial force resisted by weld in toe side;

$C_y$  = C.G of bottom chord;

$t_t$  = Throat thickness of weld = 0.7s;

$s$  = weld size;

$f_u$  = minimum of ultimate strength of truss member and welded material;

$\gamma_{m1}$  = Partial safety factor for ultimate strength;

1 = leg size of truss member section.

$$l_{wt} = \frac{P_t}{f_w} \quad (1.4)$$

$$l_{wh} = \frac{P_h}{f_w} \quad (1.5)$$

where,

$l_{wt}$  = Overall length of weld in toe side;

$l_{wh}$  = Overall length of weld in hill side;

$$l_{wteff} = l_{wt} - 2s \quad (1.6)$$

$$l_{wheff} = l_{wh} - 2s \quad (1.7)$$

where,

$l_{wteff}$  = Effective length of weld in toe side;

$l_{wheff}$  = Effective length of weld in hill side.

## Check 2

# Gusset Plate Checks

### 2.1 Whitmore Effective Width ( $B_{eff}$ )

[Reference: 5.12 Truss Joint Connection Page no. 365 Design of steel structure by N.Subramanian Edition 13th]

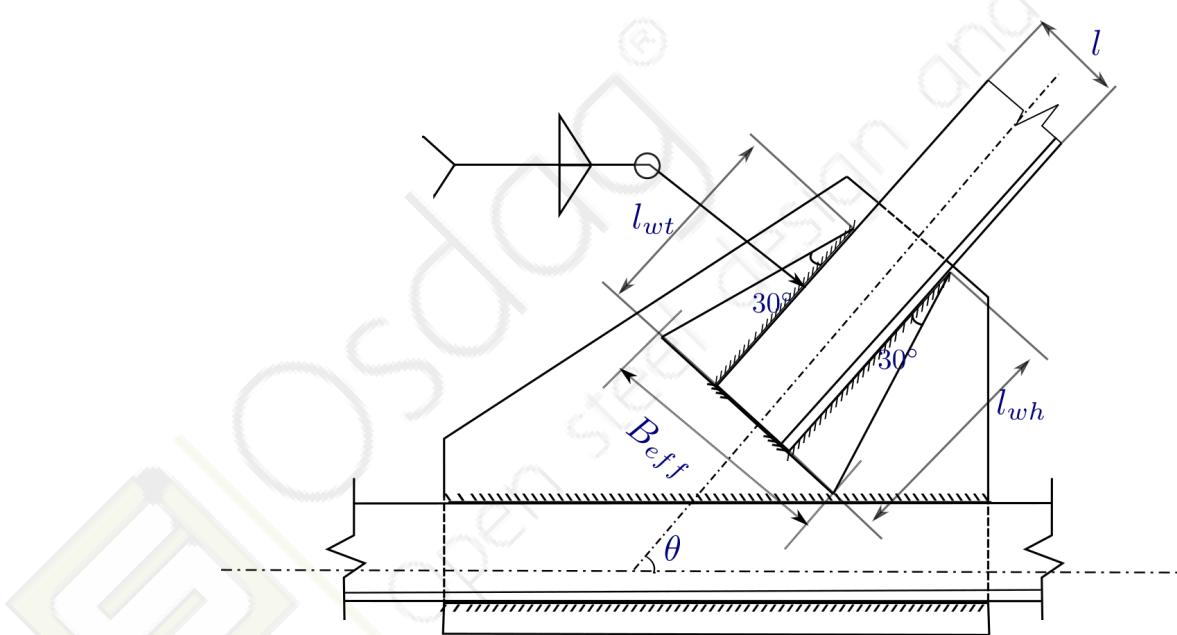


Figure 2.1: Effective Width of Gusset Plate as per Whitmore

$$B_{eff} = l + l_{wt}\tan(30^\circ) + l_{wh}\tan(30^\circ) \quad (2.1)$$

### 2.2 Check for Tension

#### 2.2.1 Check for Tension Yielding

[Reference: Cl 6.2 IS 800: 2007 ]

$$\frac{P}{(B_{eff}t_g)} \leq \frac{f_y}{\gamma_{m0}} \quad (2.2)$$

where,

$P$  = Axial force on each member;

$B_{eff}$  = Whitmore effective width;  
 $t_g$  = Gusset plate thickness;  
 $f_y$  = yield strength of plate;  
 $\gamma_{m0}$  = Partial factor of safety for yielding.

## 2.3 Compression Check

### 2.3.1 Whitmore equivalent column length ( $l_c$ )

[Reference:Design of steel by structure N.Subramanian]

$$l_c = \frac{s_0 + g_1 + g_2 \cos(\theta)}{\sin(\theta)} \quad (2.3)$$

where,

$s_0$  = spacing between bottom chord and the connected truss member;  
 $g_1$  = gauge length of bottom chord;  
 $g_2$  = gauge length of connected truss member;  
 $\theta$  = angle of inclination of connected truss member with bottom chord.

## 2.4 Check for Buckling Failure

[Reference:Cl 7.1.2.1 IS 800: 2007 ]

$$f_{cd} = \frac{f_y/\gamma_{m0}}{\phi + \sqrt{\phi^2 - \lambda^2}} \quad (2.4)$$

where,

$\phi = 0.5[1 + \alpha(\lambda - 0.2) + \lambda^2]$   
 $\lambda$  = non-dimensional effective slenderness ratio;  
 $=\sqrt{f_y/f_{cc}}$   
 $f_{cc}$  = Euler Buckling stress =  $\frac{\pi^2 E}{(K l_c / r_{min})^2}$   
 $K$  = 0.7, Effective length factor;  
 $l_c$  = Whitmore equivalent column length;  
 $r_{min}$  = radius of gyration of plate =  $t_g/\sqrt{12}$ ;

$f_{cd}$  = Design Compressive stress;

$t_g$  = Thickness of gusset plate.

$$\frac{F}{B_{eff} t_g} \leq f_{cd} \quad (2.5)$$

where,

$F$  = Axial force on truss member;  
 $B_{eff}$  = Whitmore effective width.

## 2.5 Block Failure of Gusset Plate

[Reference:Cl 6.4.1 IS 800: 2007 ]

In case of welded connection gusset plate may fail by block shear may occur.

$$T_{db1} = \frac{A_{vg} f_y}{\sqrt{3} \gamma_{m0}} + \frac{0.9 A_{tn} f_u}{\gamma_{m1}} \quad (2.6)$$

$$T_{db2} = \frac{0.9A_{vn}f_u}{\sqrt{3}\gamma_{m1}} + \frac{A_{tg}f_y}{\gamma_{m0}} \quad (2.7)$$

where,

$A_{vg}$  = Minimum gross area in shear along bolt line parallel to external force =  $l_v * t$

$A_{vn}$  = Minimum net area in shear along bolt line parallel to external force =  $l_v * t$

$A_{tg}$  = Minimum gross area in tension from the bolt hole to the toe of the angle, end bolt line, perpendicular to the line of force =  $l_t * t$

$A_{tn}$  = Minimum net area in tension from the bolt hole to the toe of the angle, end bolt line, perpendicular to the line of force =  $l_t * t$

$f_u$  = Ultimate stress of the plate material

$f_y$  = Yield stress of the plate material

$\gamma_{m0} = 1.10$

$\gamma_{m1} = 1.25$

## Check 3

# Detailing

### 3.1 Gusset plate Dimensions

#### 3.1.1 Height of Gusset plate ( $h_g$ )

Height of gusset plate is based on maximum weld length and angle of inclination of truss member with C.G of bottom chord.

$$h_g = \max(l_c + l_w) \sin(\theta) \quad (3.1)$$

where,

$l_w$  = weld length of diagonal or vertical truss member;

$l_c$  = Whitmore equivalent column length;

$\theta$  angle of inclination of truss member with C.G of bottom chord.

#### 3.1.2 Width of gusset plate ( $w_g$ )

Width of gusset plate is equal to weld length of bottom chord.

$$w_g = L_{wb} \quad (3.2)$$

where,

$L_{wb}$  = Length of weld for bottom chord.