# CFD using OpenFOAM Lecture 6: Essential Flow Governing Laws & OpenFOAM Implementation

Part II : Discretisation of Flow Governing Laws













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Control Volume Notations

Mass Conservation

Momentum Conservation

Discretisation Scheme

Challenges and Solution



▶ Framework : Eulerian and Lagrangian



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- ▶ Conservation Equations in Fluid Dynamics



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Conservation Equations in Fluid Dynamics

► Mass Conservation (2D):

Continuity: 
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$



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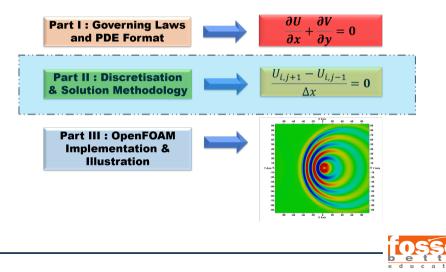
Continuity: 
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Momentum Conservation (2D):  

$$x$$
-Momentum:  $\rho \frac{\partial u}{\partial t} + \rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) - \frac{\partial p}{\partial x}$   
 $y$ -Momentum:  $\rho \frac{\partial v}{\partial t} + \rho u \frac{\partial v}{\partial x} + \rho v \frac{\partial v}{\partial y} = \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \frac{\partial p}{\partial y}$ 



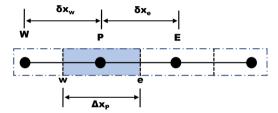
Division of contents for CFD & OpenFOAM Implementation



▶ The following figure indicates a 1D Control Volume (C.V) with notations



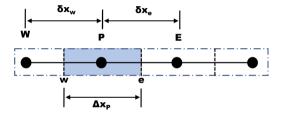
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Notations used for Finite Volume Discretisation

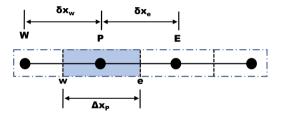
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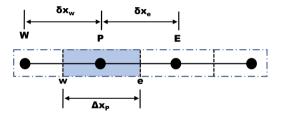


$$\begin{split} \mathbf{P} &\rightarrow \mathbf{Centroid} \text{ of } \mathbf{C.V} \\ \mathbf{W,E} &\rightarrow \mathbf{Centroid} \text{ of neighbouring} \\ \mathbf{C.V's} \\ \mathbf{w,e} &\rightarrow \mathbf{Faces} \text{ of } \mathbf{C.V} \end{split}$$

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 Gauss divergence theorem is extensively used in Finite-Volume-Method (FVM) to obtain discrete equation

$$\int \int_{V} \int (\vec{\nabla} \cdot \vec{F}) dV = \int \int_{A} (\vec{F} \cdot \vec{n}) dA \tag{1}$$



$$\frac{\partial(\rho u_x)}{\partial x} = 0 \tag{2}$$

where  $u_x$  denotes velocity in x direction.



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$$\implies (\rho u_{x})_{e} - (\rho u_{x})_{w} = 0$$



$$\frac{\partial(\rho u_x)}{\partial t} + u_x \frac{\partial(\rho u_x)}{\partial x} = -\frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\mu \frac{\partial u_x}{\partial x}\right) \tag{3}$$



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• Upon Finite Volume (FV) integration, the discrete equation can be obtained as follows (after using Gauss-divergence theorem for  $2^{nd}$ ,  $3^{rd}$  &  $4^{th}$  term):



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$$\frac{\rho\left(u_x^{t+\Delta t}-u_x^t\right)}{\Delta t}\Delta x_P + \int \int_A u_x(\rho u_x)dA = -\int \int_A pdA + \int \int_A \mu \frac{\partial u_x}{\partial x}dA$$



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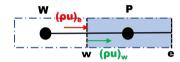
$$\frac{\rho\left(u_x^{t+\Delta t} - u_x^t\right)}{\Delta t} \Delta x_P + \int \int_A u_x(\rho u_x) dA = -\int \int_A p dA + \int \int_A \mu \frac{\partial u_x}{\partial x} dA$$

$$\implies \frac{\rho\left(u_x^{t+\Delta t} - u_x^t\right)}{\Delta t} + (u_x \rho u_x)_e - (u_x \rho u_x)_w = -(p_e - p_w) + (\mu \frac{\partial u_x}{\partial x})_e - (\mu \frac{\partial u_x}{\partial x})_w$$



#### 1. Conservativeness:

(flux out of a C.V) = (flux in of neighbouring C.V)



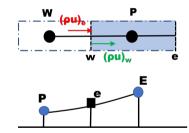


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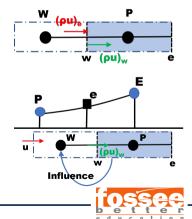
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#### 3. Transportiveness:

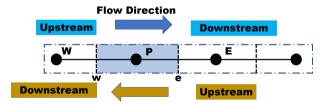
Calculation of variable value/gradient should consider effect of flow into account



$$\phi_e = \frac{\Delta V_P \phi_E + \Delta V_E \phi_P}{\Delta V_P + \Delta V_E}; \phi_w = \frac{\Delta V_P \phi_W + \Delta V_W \phi_P}{\Delta V_P + \Delta V_W} \tag{4}$$



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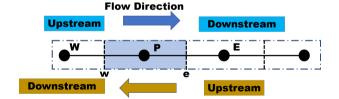


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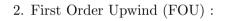
2. First Order Upwind (FOU) :

$$\phi_f = \phi_U \tag{5}$$





$$\phi_e = \frac{\Delta V_P \phi_E + \Delta V_E \phi_P}{\Delta V_P + \Delta V_E}; \phi_w = \frac{\Delta V_P \phi_W + \Delta V_W \phi_P}{\Delta V_P + \Delta V_W} \tag{4}$$

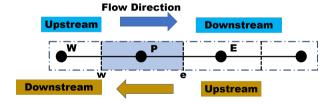


$$\phi_f = \phi_U \tag{5}$$

3. Second Order Upwind (SOU) :

$$\phi_f = 1.5\phi_U - 0.5\phi_{UU} \quad (6)$$





Advection term consists of  $u_x(\rho u_x)$  term, the equation becomes non-linear **Solution** : velocity in mass-flux is time-lagged (i.e., in  $\rho u_x$ ,  $u_x^t$  is used)



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# ▶ Non-availability of Explicit Pressure Equation:

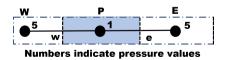
Equations : (1) Continuity : Involves velocity only (2) Momentum : Used to calculate the velocity



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## Pressure-Velocity Decoupling:

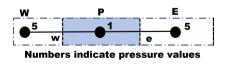




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# Pressure-Velocity Decoupling:



$$\frac{\partial p}{\partial x} = (p_e - p_w)/\Delta x_P$$
$$\frac{\partial p}{\partial x} = \frac{\left((P_E + P_P) - (P_W + P_P)\right)}{(2\Delta x_P)} = 0$$



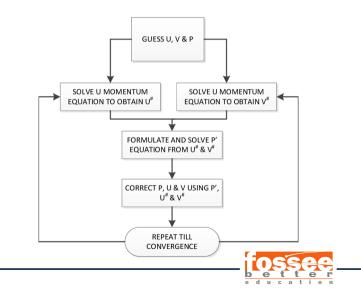


In order to address the issue of non-availability of specific pressure equation in conservation laws, a predictor corrector approach named as 'Semi-Implicit Method for Pressure Linked Equations' (SIMPLE) is employed as given below





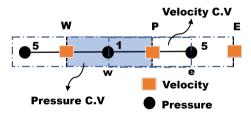
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▶ In order to avoid pressure-velocity decoupling, a staggered grid arrangement is employed as shown :

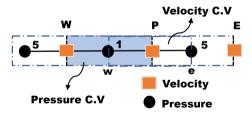


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$$\frac{\partial p}{\partial x} = (p_e - p_w) / \Delta x_P$$
$$\frac{\partial p}{\partial x} = \frac{((P_E) - (P_P))}{(\Delta x_P)} = \frac{4}{\Delta x_P}$$





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- 1. Control Volume Notations
- 2. Discretisation Procedure for Mass Conservation





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- 2. Discretisation Procedure for Mass Conservation
- 3. Discretisation Procedure for Momentum Conservation





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- 4. Properties of discretisation scheme





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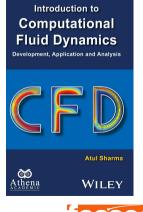
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In the next lecture, we shall look into the implementation details in OpenFOAM code and see a sample example.



# References

- Sharma, A. (2016). Introduction to computational fluid dynamics: development, application and analysis. John Wiley & Sons.
- 2. NPTEL AE 20 Course (https://nptel.ac.in/courses/101105085)
- 3. https://www.openfoam.com/





Thank you for listening!

Sumant R Morab

